Network Flows

Admin/Announcements

- CS Preregistration Info Session during Colloquium. Learn about:
 - courses offered next semester
 - major applications & forms
 - thesis applications & timelines
 - study abroad guidelines
- TAs and becoming a TA
 - Fill out <u>TA feedback</u> forms by Monday
 - Submit <u>TA applications</u> by April 21
- Williams Entrepreneurship Summit this Saturday!

Story So Far

- Algorithmic design paradigms:
 - Greedy: often simplest algorithms to design, but only work for certain limited class of optimization problems
 - A good initial thought for most problems but rarely optimal

Divide and Conquer

 Solving a problem by breaking it down into smaller subproblems and (often) combining results

Dynamic programming

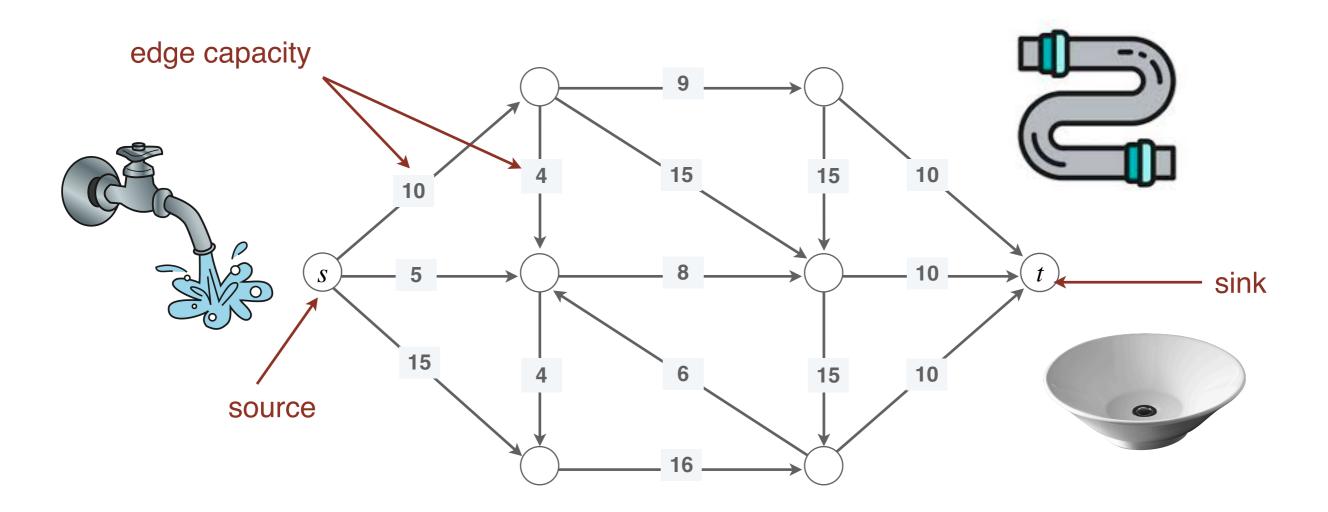
- Recursion with memoization: avoiding repeated work
- Trade space (memoization structure representation) for time (reuse stored results of repeated computations)

New Algorithmic Paradigm

- Network flows model a variety of optimization problems
- These optimization problems look complicated with lots of constraints
 - At first they may seem to have nothing to do with networks or flows!
- Very powerful problem solving frameworks
- We'll focus on the concept of problem reductions
 - Problem A reduces to B if a solution to B leads to a solution to A
- We'll learn how to prove that our reductions are correct

What's a Flow Network?

- A flow network is a directed graph G = (V, E) with a
 - A **source** is a vertex s with in-degree 0
 - A **sink** is a vertex t with out-degree 0
 - Each edge $e \in E$ has edge capacity c(e) > 0



Assumptions

- Assume that each node v is on some s-t path, that is, $s \leadsto v \leadsto t$ exists, for any vertex $v \in V$
 - Implies G is connected and $m \ge n-1$
- Assume capacities are positive integers
 - Will revisit this assumption & what happens otherwise
- Directed edge (u, v) written as $u \to v$
- For simplifying expositions, we will sometimes write $c(u \rightarrow v) = 0$ when $(u, v) \notin E$

What's a Flow?

- Given a flow network, an (s, t)-flow or just flow (if source s and sink t are clear from context) $f: E \to \mathbb{Z}^+$ satisfies the following two constraints:
- [Flow conservation] $f_{in}(v) = f_{out}(v)$, for $v \neq s, t$ where

$$f_{in}(v) = \sum_{u} f(u \to v)$$

$$f_{out}(v) = \sum_{w} f(v \to w)$$

$$f_{out}(v) = \int_{w} f(v \to w)$$

flow

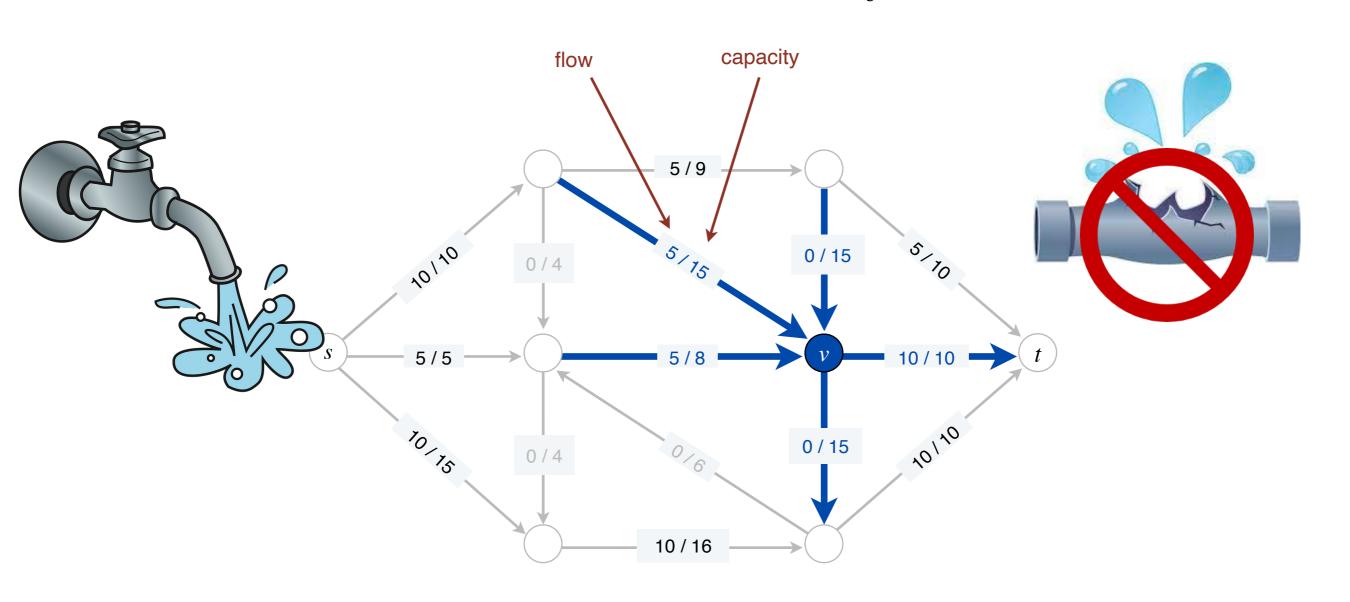
capacity

• To simplify, $f(u \rightarrow v) = 0$ if there is no edge from u to v

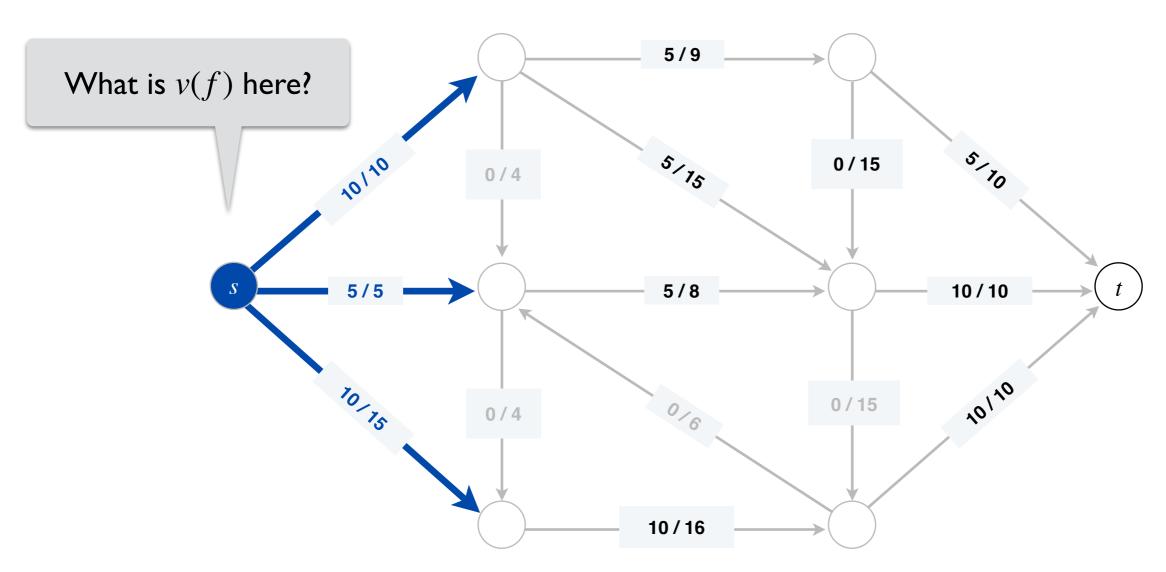
Feasible Flow

 And second, a feasible flow must satisfy the capacity constraints of the network, that is,

[Capacity constraint] for each $e \in E$, $0 \le f(e) \le c(e)$



• **Definition.** The **value** of a flow f, written v(f), is $f_{out}(s)$.

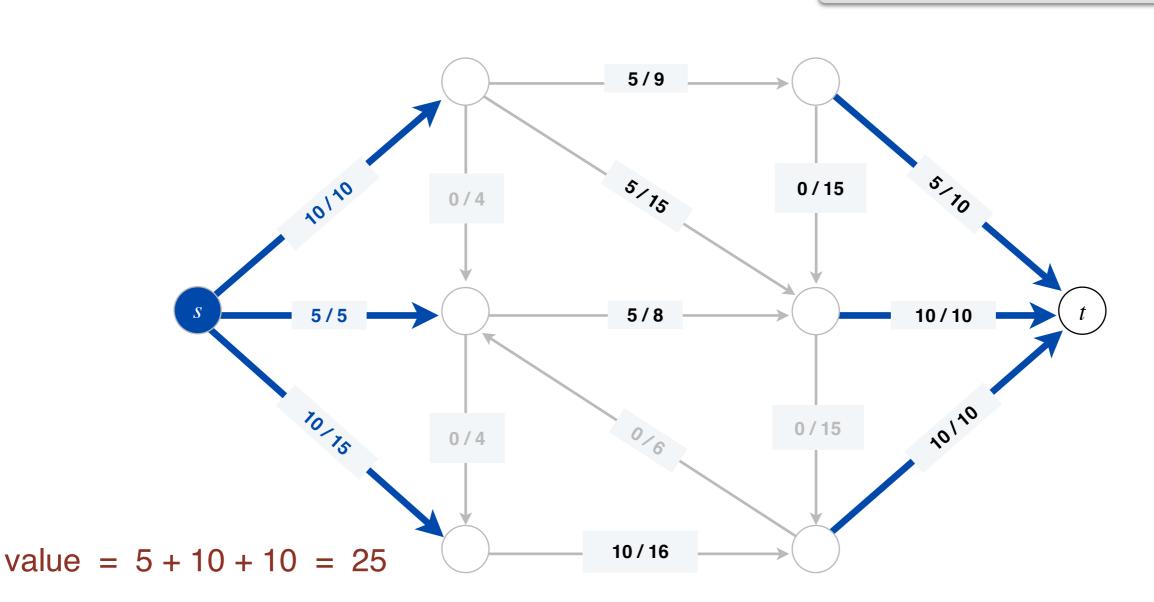


$$v(f) = 5 + 10 + 10 = 25$$

• **Definition.** The **value** of a flow f, written v(f), is $f_{out}(s)$.



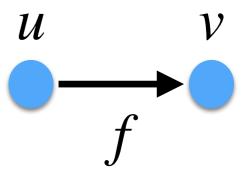
Intuitively, why do you think this is true?



Lemma. $f_{out}(s) = f_{in}(t)$

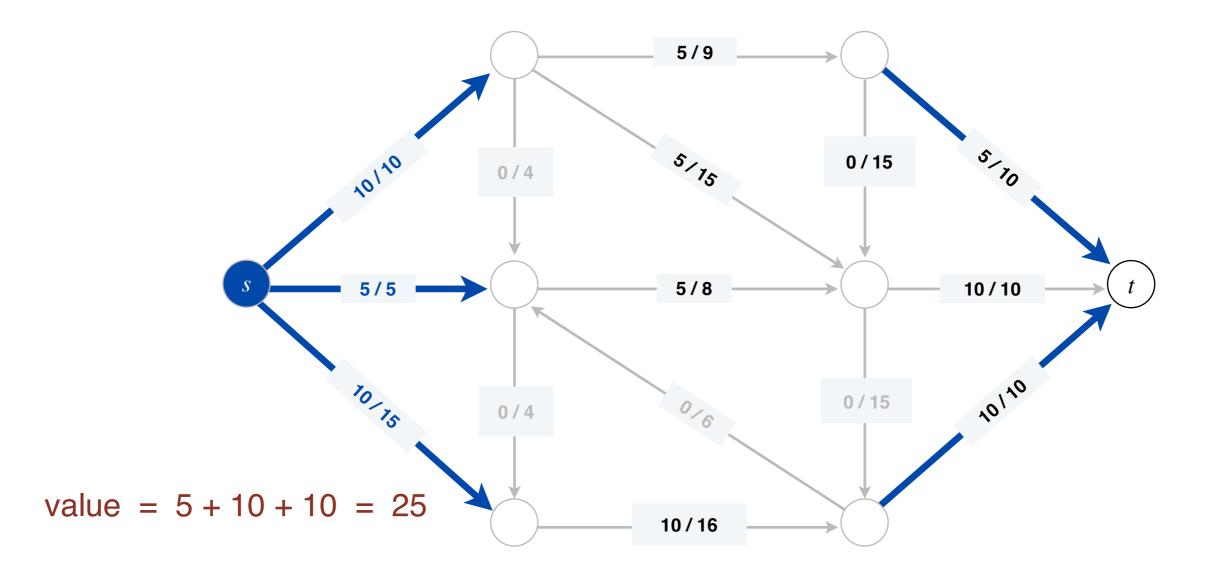
Proof. Let
$$f(E) = \sum_{e \in E} f(e)$$

Then,
$$\sum_{v \in V} f_{in}(v) = f(E) = \sum_{v \in V} f_{out}(v)$$



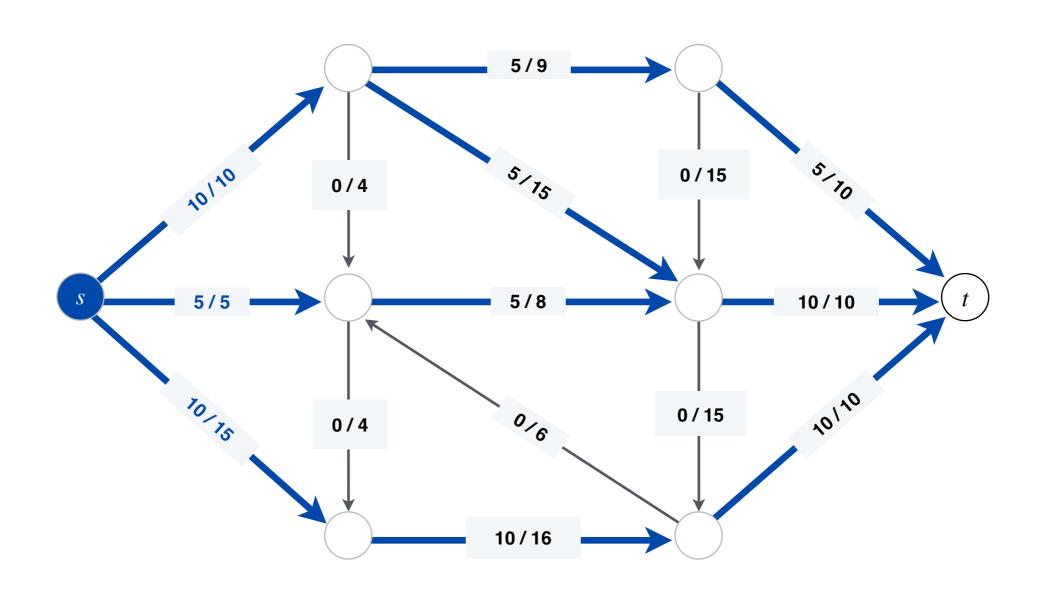
- For every $v \neq s, t$ flow conservation implies $f_{in}(v) = f_{out}(v)$
- Thus all terms cancel out on both sides except $f_{in}(s) + f_{in}(t) = f_{out}(s) + f_{out}(t)$
- But $f_{in}(s) = f_{out}(t) = 0$

- Lemma. $f_{out}(s) = f_{in}(t)$
- Corollary. $v(f) = f_{in}(t)$.



Max-Flow Problem

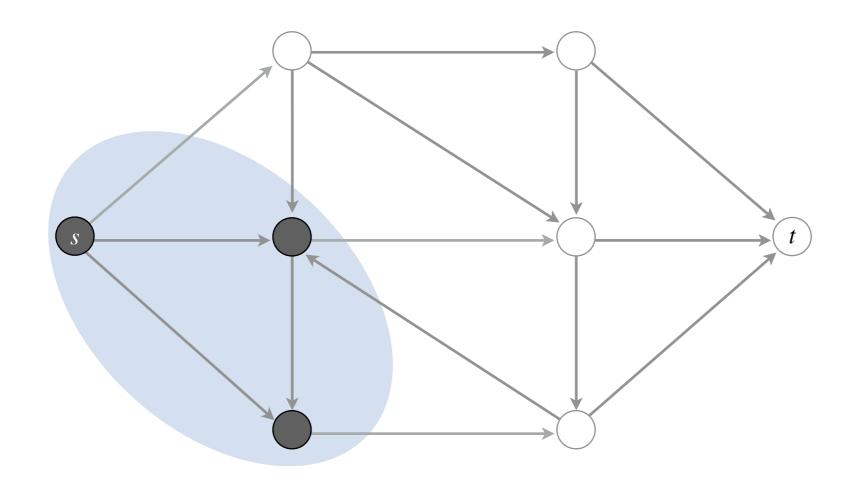
 Problem. Given an s-t flow network, find a feasible s-t flow of maximum value.



Minimum Cut Problem

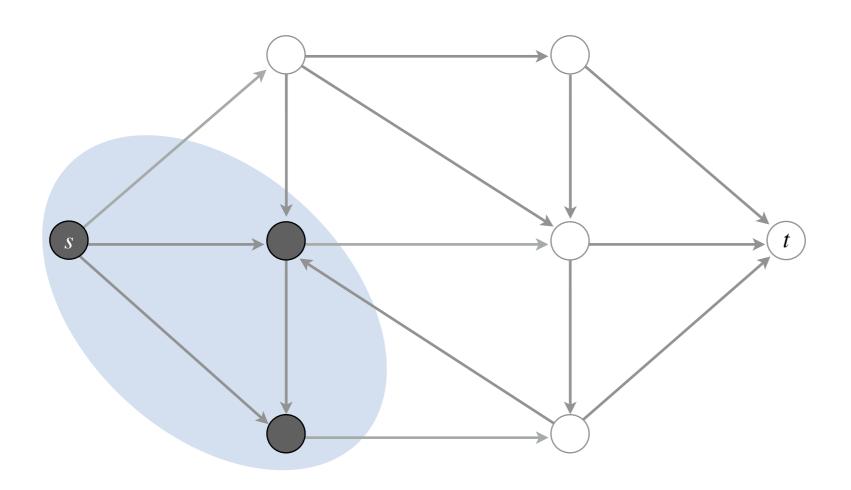
Cuts are Back!

- Cuts in graphs played a key role when we were designing algorithms for MSTs
- What is the definition of a cut?



Cuts in Flow Networks

- Recall. A cut (S,T) in a graph is a partition of vertices such that $S \cup T = V$, $S \cap T = \emptyset$ and S,T are non-empty.
- **Definition**. An (s, t)-cut is a cut (S, T) s.t. $s \in S$ and $t \in T$.



Cut Capacity

- Recall. A cut (S,T) in a graph is a partition of vertices such that $S \cup T = V$, $S \cap T = \emptyset$ and S,T are non-empty.
- **Definition**. An (s, t)-cut is a cut (S, T) s.t. $s \in S$ and $t \in T$.
- Capacity of a (s, t)-cut (S, T) is the sum of the capacities of edges leaving S:

$$c(S,T) = \sum_{v \in S, w \in T} c(v \to w)$$

Quick Quiz

Question. What is the capacity of the *s-t* cut given by grey and white nodes?

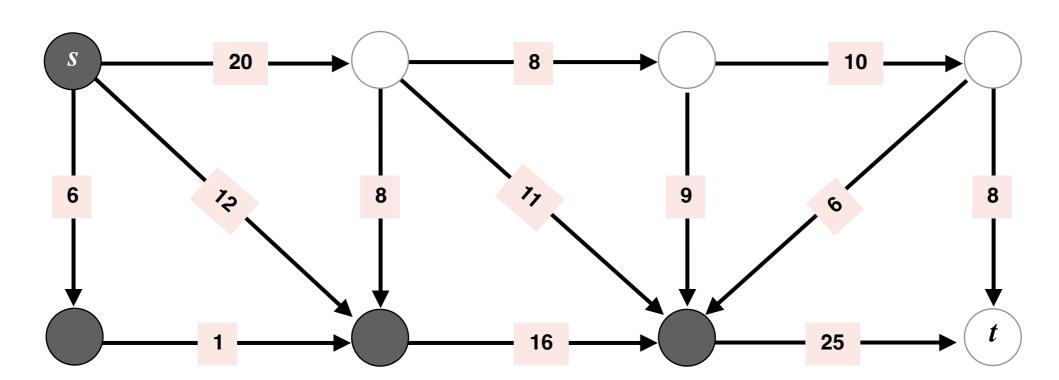
 $c(S,T) = \sum c(v \to w)$

 $v \in S, w \in T$

A. 11
$$(20 + 25 - 8 - 11 - 9 - 6)$$

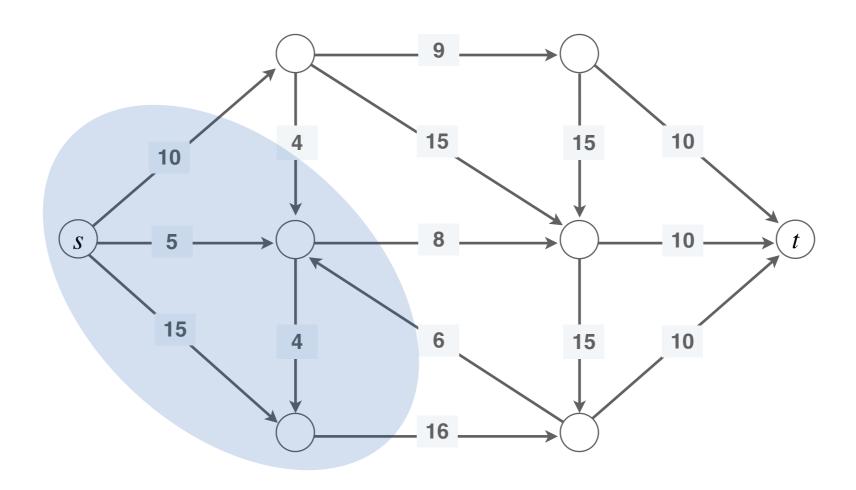
C.
$$45 (20 + 25)$$

D. 79
$$(20 + 25 + 8 + 11 + 9 + 6)$$



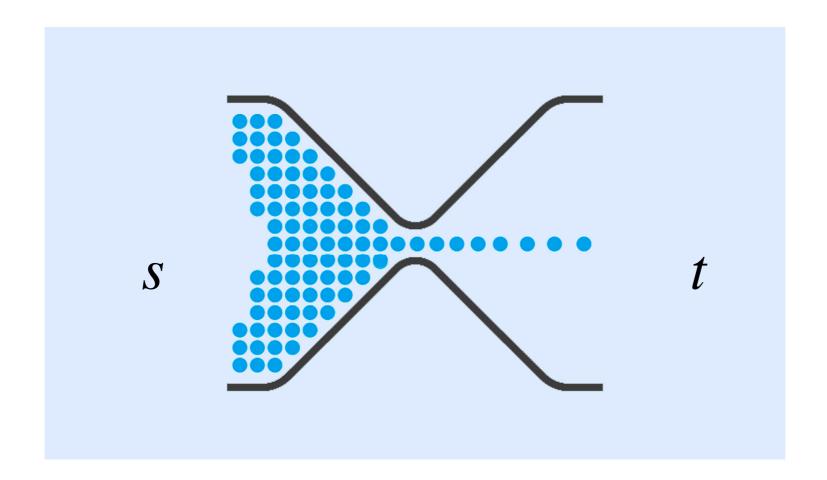
Min Cut Problem

 Problem. Given an s-t flow network, find an s-t cut of minimum capacity.



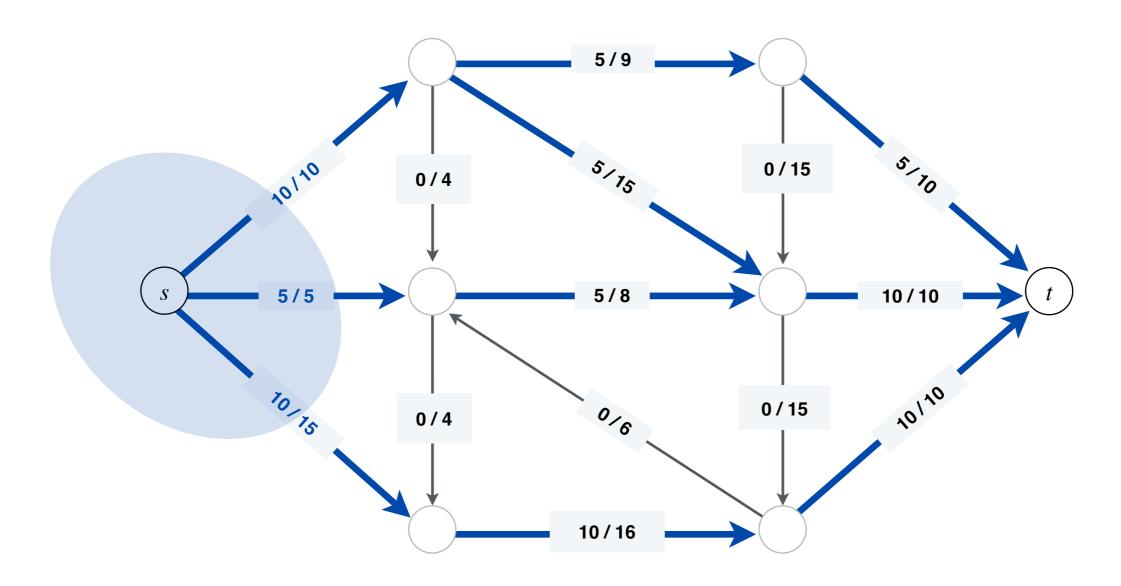
Relationship between Flows and Cuts

- Cuts represent "bottlenecks" in a flow network
- For any (s, t)-cut, all flow needs to "exit" S to get to t
- We will formalize this intuition



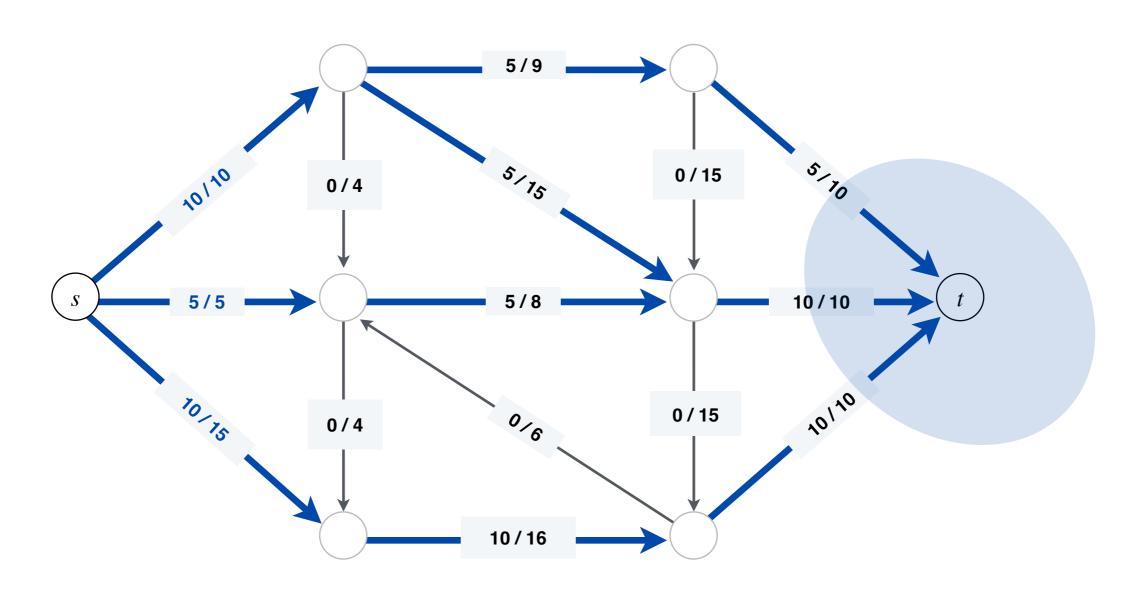
Claim. Let f be any s-t flow and (S, T) be any s-t cut then $v(f) \le c(S, T)$

• There are two *s-t* cuts for which this is easy to see (which ones?)



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To prove this for any cut, we first relate the flow value in a network to the **net flow** leaving a cut

• **Lemma**. For any feasible (s, t)-flow f on G = (V, E) and any (s, t)-cut, $v(f) = f_{out}(S) - f_{in}(S)$, where

$$f_{out}(S) = \sum_{v \in S, w \in T} f(v \to w) \text{ (sum of flow 'leaving' } S)$$

$$f_{in}(S) = \sum_{v \in S, w \in T} f(w \to v) \text{ (sum of flow 'entering' } S)$$

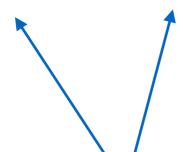
• Note: $f_{out}(S) = f_{in}(T)$ and $f_{in}(S) = f_{out}(T)$

Proof. $f_{out}(S) - f_{in}(S)$

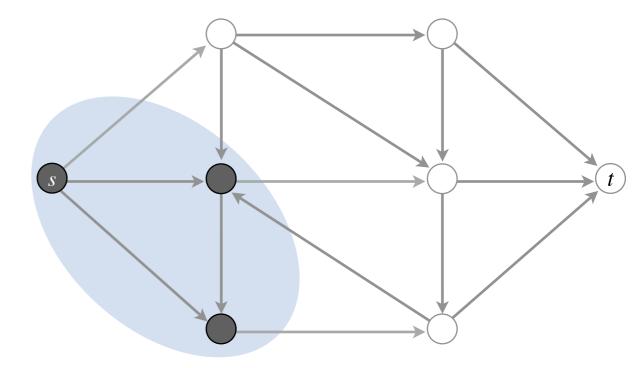
$$= \sum_{v \in S, w \in T} f(v \to w) - \sum_{v \in S, u \in T} f(u \to v)$$
 [by definition]

Adding zero terms

$$= \left[\sum_{v,w\in S} f(v\to w) - \sum_{v,u\in S} f(u\to v)\right] + \sum_{v\in S,w\in T} f(v\to w) - \sum_{v\in S,u\in T} f(u\to v)$$



These are the same sum: they sum the flow of all edges with both vertices in S



Proof. $f_{out}(S) - f_{in}(S)$

Rearranging terms

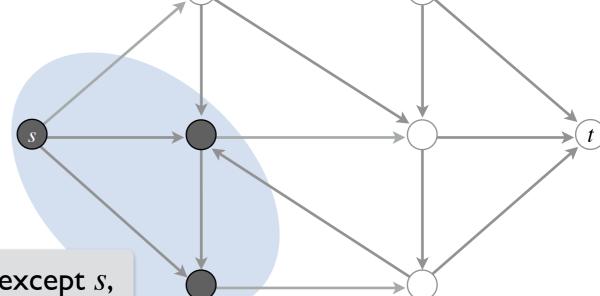
$$= \left[\sum_{v,w\in S} f(v\to w) - \sum_{v,u\in S} f(u\to v)\right] + \sum_{v\in S,w\in T} f(v\to w) - \sum_{v\in S,u\in T} f(u\to v)$$

$$= \sum_{v,w \in S} f(v \to w) + \sum_{v \in S,w \in T} f(v \to w) - \sum_{v,u \in S} f(u \to v) - \sum_{v \in S,u \in T} f(u \to v)$$

$$= \sum_{v \in S} \left(\sum_{w} f(v \to w) - \sum_{u} f(u \to v) \right)$$

$$= \sum_{v \in S} f_{out}(v) - f_{in}(v)$$

$$= f_{out}(s) = v(f)$$



Cancels out for all except s, which has no f_{in}

- We use this result to prove that the value of a flow cannot exceed the capacity of <u>any</u> cut in the network.
- Claim. Let f be any s-t flow and (S,T) be any s-t cut then $v(f) \leq c(S,T)$ Sum of capacities leaving S
- Proof. $v(f) = f_{out}(S) f_{in}(S)$

$$\leq f_{out}(S) = \sum_{v \in S, w \in T} f(v \to w)$$

$$\leq \sum_{v \in S, w \in T} c(v, w) = c(S, T)$$

When is v(f) = c(S, T)?

$$f_{in}(S) = 0, f_{out}(S) = c(S, T)$$

Max-Flow & Min-Cut

- Suppose the c_{\min} is the capacity of the \min minimum cut in a network
- What can we say about the feasible flow we can send through it
 - cannot be more than c_{\min}
- In fact, whenever we find any s-t flow f and any s-t cut (S,T) such that, v(f)=c(S,T) we can conclude that:
 - f is the maximum flow, and,
 - (S,T) is the minimum cut
- The question now is, given any flow network with min cut c_{\min} , is it always possible to route a feasible s-t flow f with $v(f)=c_{\min}$?

Max-Flow Min-Cut Theorem

There is a beautiful, powerful relationship between these two problems in given by the following theorem.

• Theorem. Given any flow network G, there exists a feasible (s,t)-flow f and an (s,t)-cut (S,T) such that,

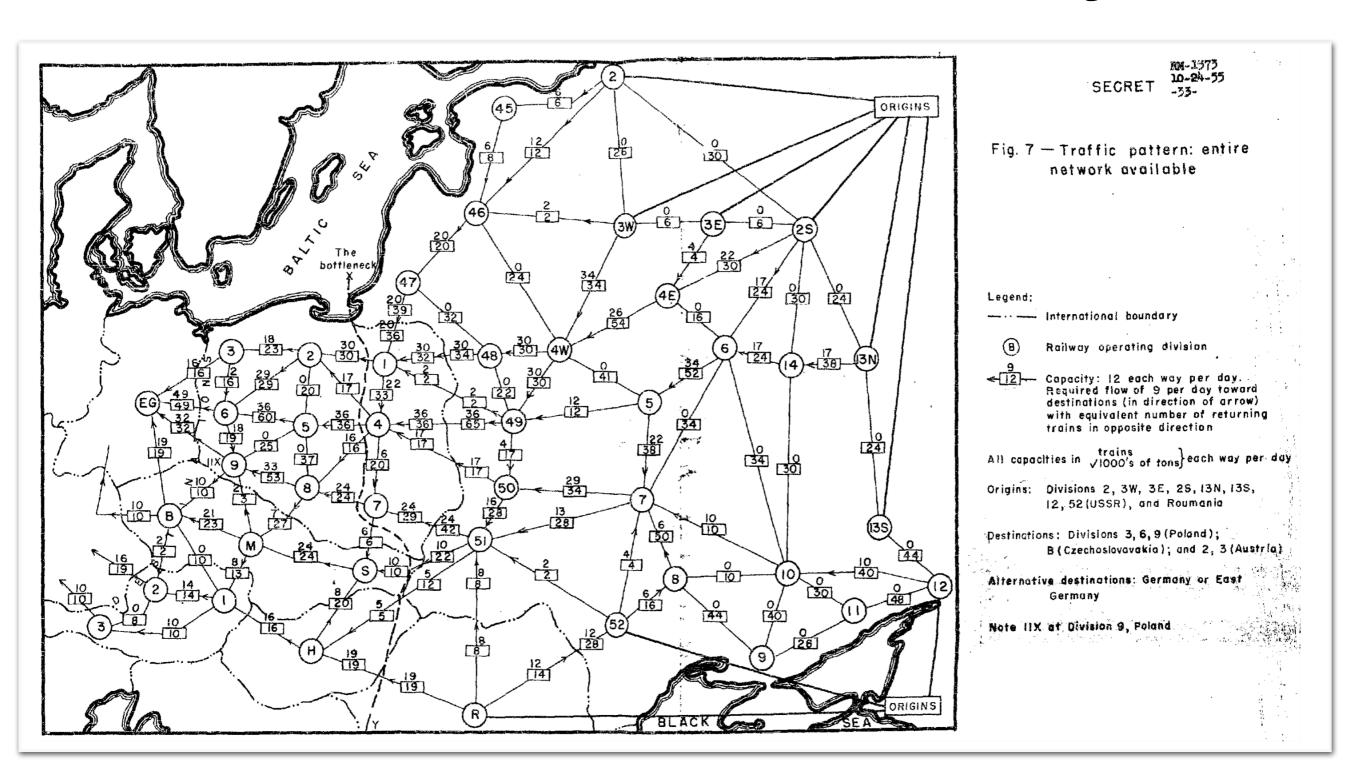
$$v(f) = c(S, T)$$

- Informally, in a flow network, the max-flow = min-cut
- This will guide our algorithm design for finding max flow
- (Will prove this theorem by construction in a bit.)

Aside: Network Flow History

- In 1950s, US military researchers Harris and Ross wrote a classified report about the rail network linking Soviet Union and Eastern Europe
 - Vertices were the geographic regions
 - Edges were railway links between the regions
 - Edge weights were the rate at which material could be shipped from one region to next
- Ross and Harris determined:
 - Maximum amount of stuff that could be moved from Russia to Europe (max flow)
 - Cheapest way to disrupt the network by removing rail links (min cut)

Network Flow History



Ford-Fulkerson Algorithm

We will design a max-flow algorithm and show that there is a s-t cut s.t. value of flow computed by algorithm = capacity of cut

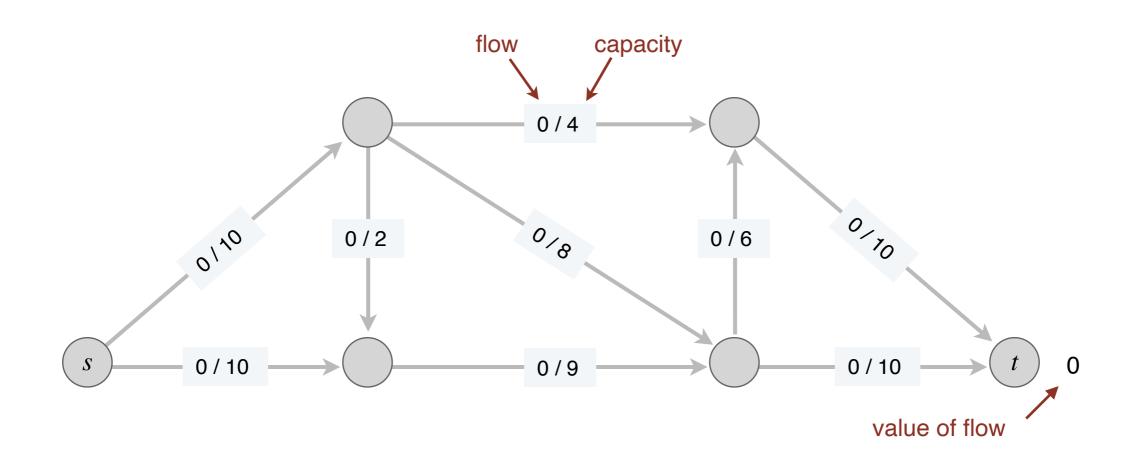
- Let's start with a greedy approach:
 - Pick an s-t path and push as much flow as possible down it
 - Repeat until you get stuck

Note: This won't actually work, but it gives us a sense of what we need to keep track of to improve it

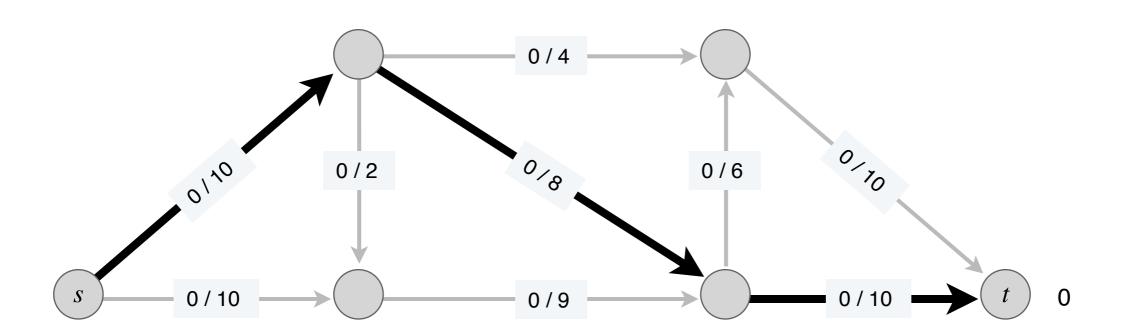
Greedy strategy:

- Start with f(e) = 0 for each edge
- Find an $s \sim t$ path P where each edge has f(e) < c(e)
- "Augment" flow (as much as possible) along path P
- Repeat until you get stuck
- Let's explore an example

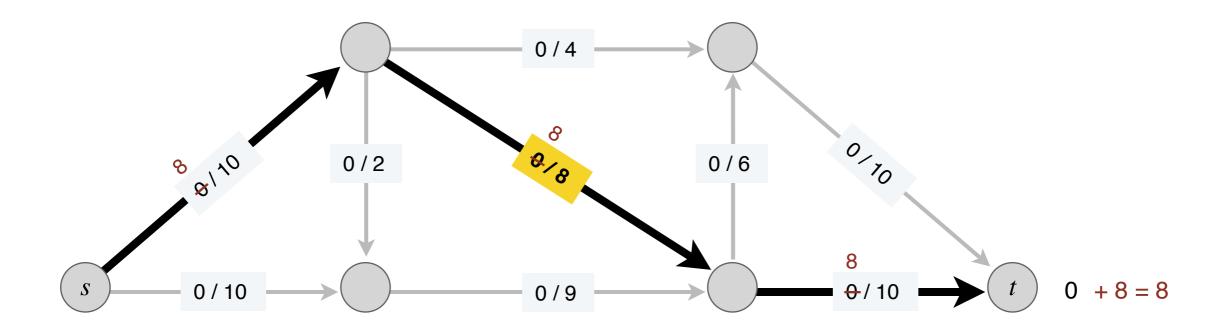
- Start with f(e) = 0 for each edge
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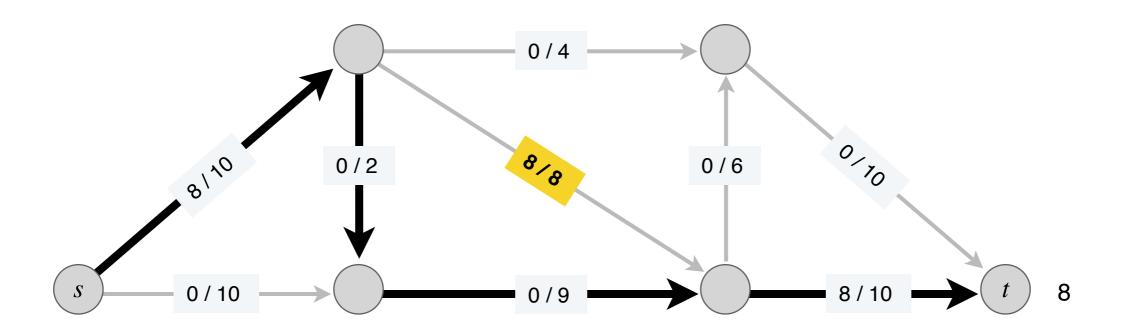
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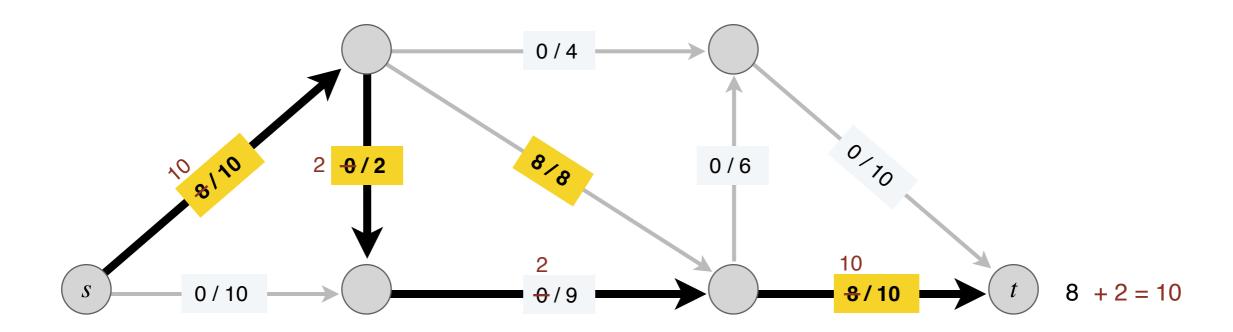
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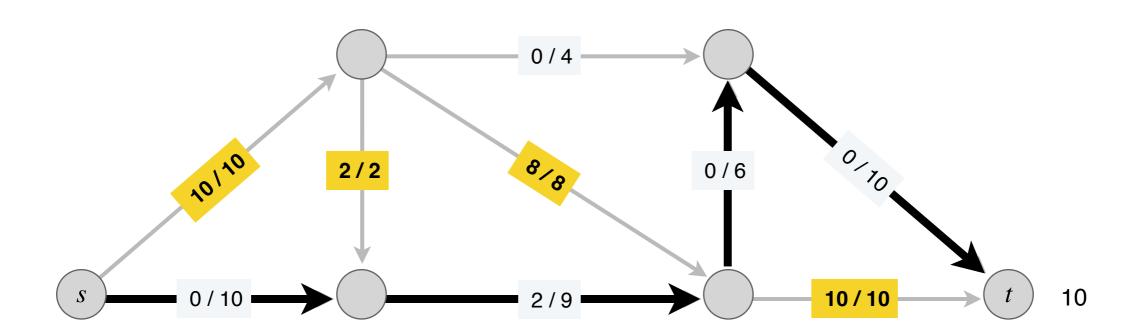
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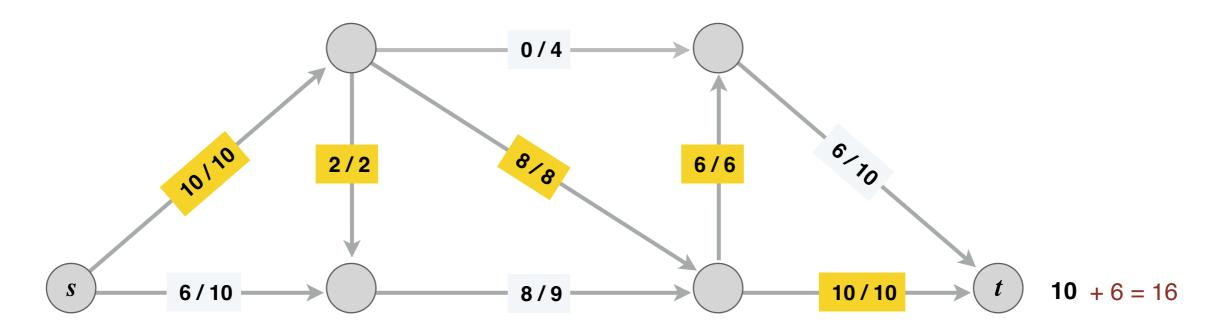


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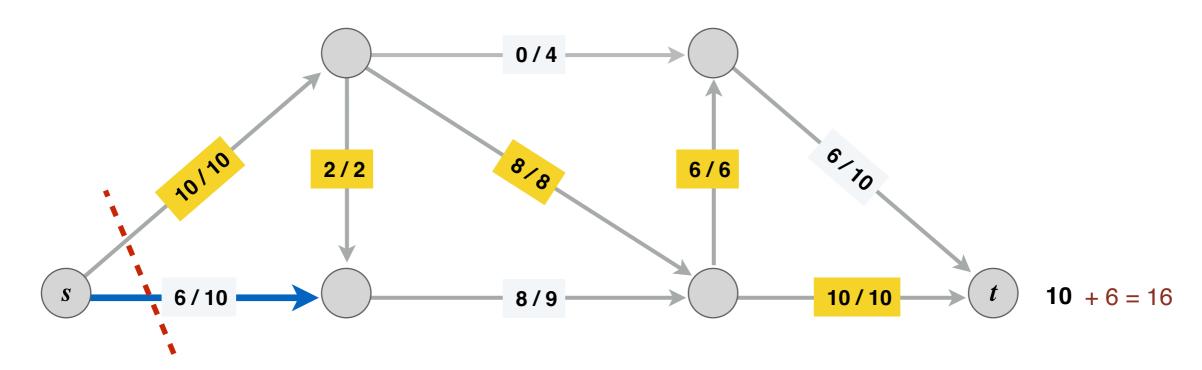


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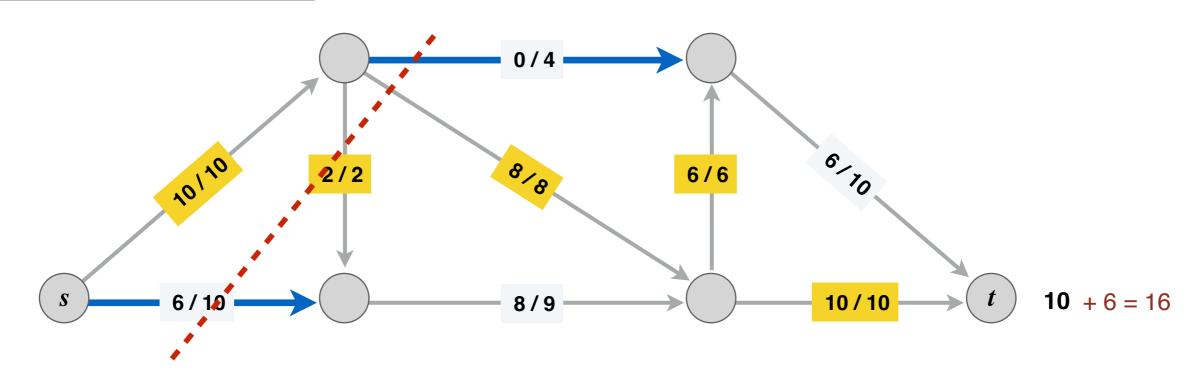
Is this the best we can do?



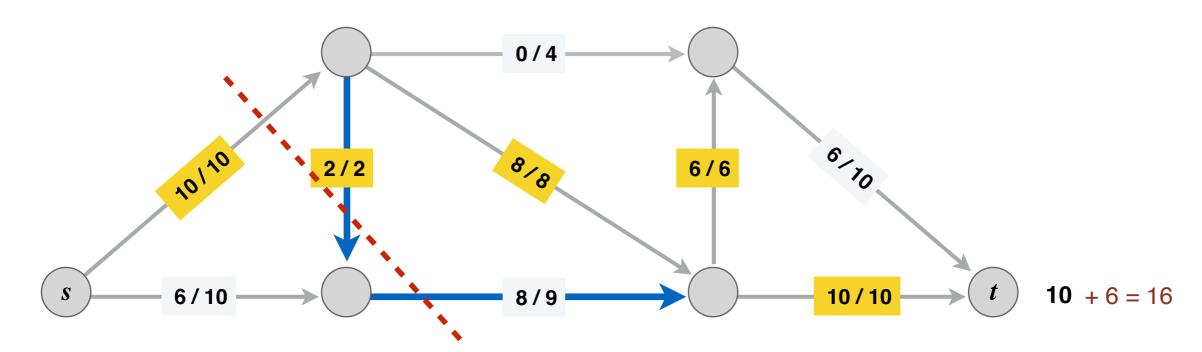
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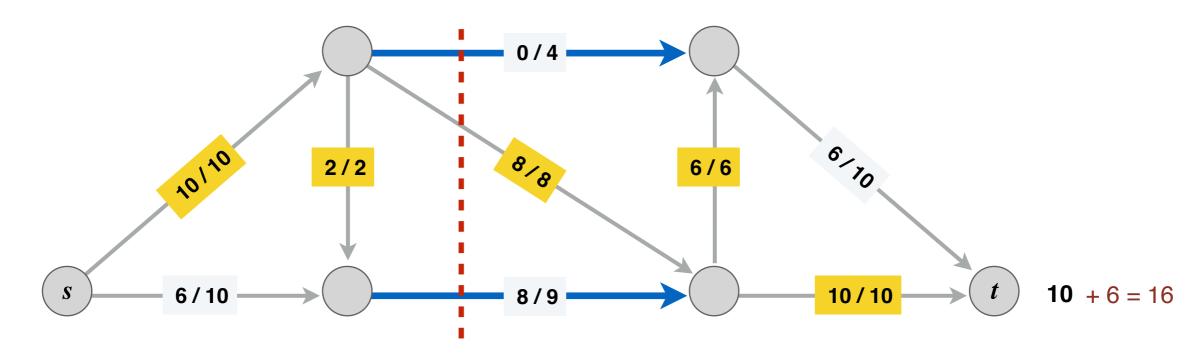
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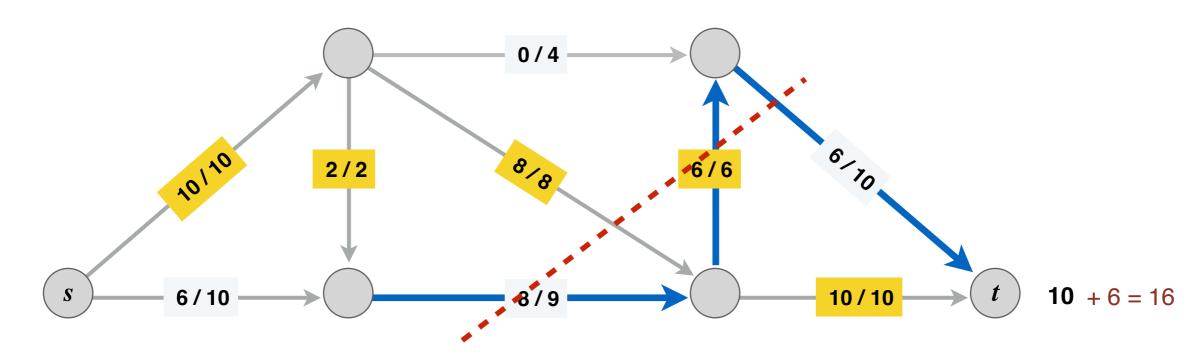
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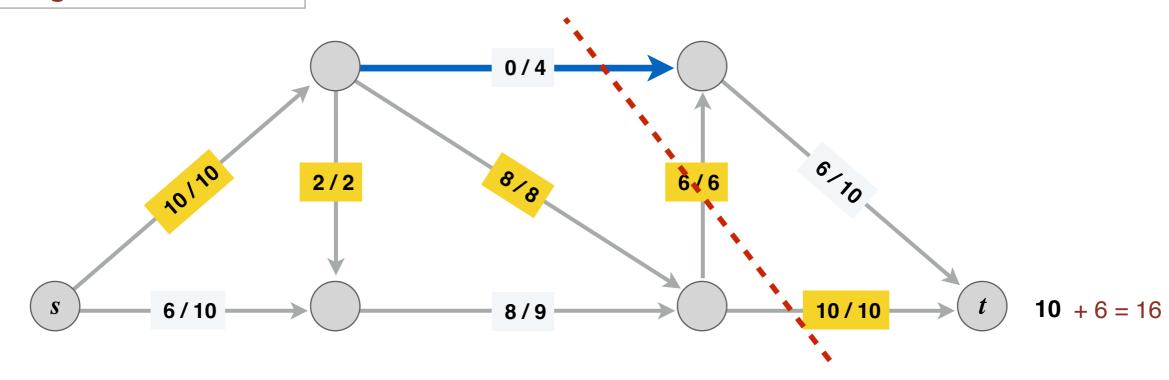
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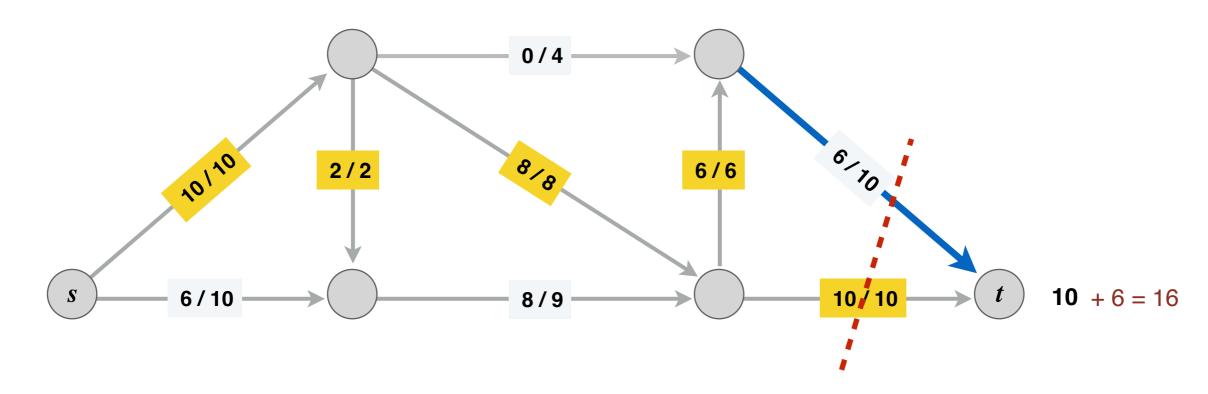
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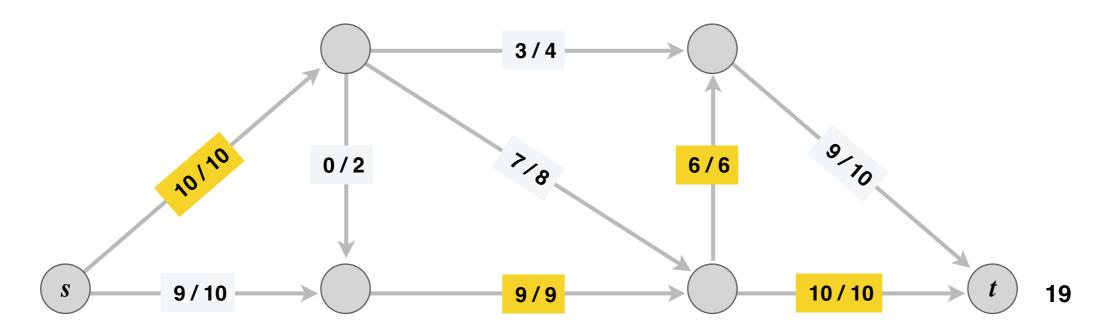


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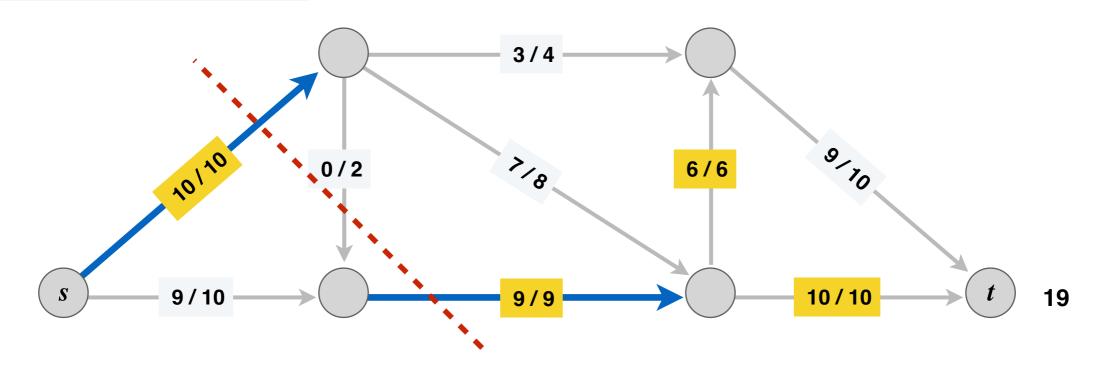
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max-flow value = 19



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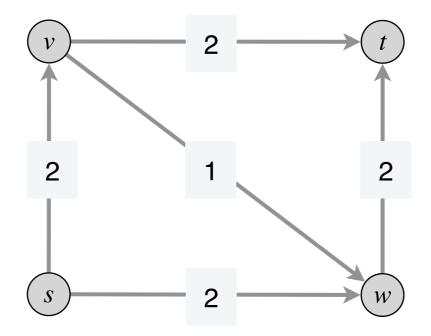
max-flow value = 19



Why Greedy Fails

Problem: greedy can never "undo" a bad flow decision

Consider the following flow network



- Greedy could choose $s \to v \to w \to t$ as first P
- Takeaway: Need a mechanism to "undo" bad flow decisions

Ford-Fulkerson Algorithm

Ford Fulkerson: Idea

Goal: Want to make "forward progress" while letting ourselves undo previous decisions if they're getting in our way

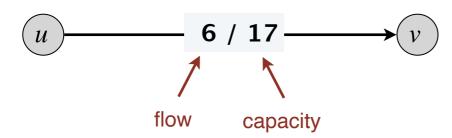
- Idea: keep track of where we can push flow
 - Can push more flow along any edge with remaining capacity
 - Can also push flow "back" along any edge that already has flow down it (undo a previous flow push)
- We need a way to systematically track these decisions

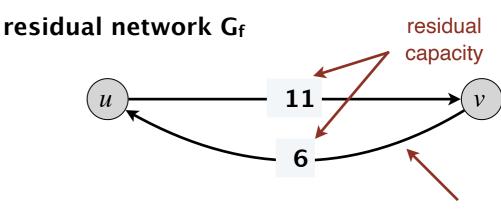
Residual Graph

Given flow network G = (V, E, c) and a feasible flow f on G, the residual graph $G_f = (V, E_f, c_f)$ is defined as follows:

- Vertices in G_f same as G
- (Forward edge) For $e \in E$ with residual capacity c(e) f(e) > 0, create $e \in E_f$ with capacity c(e) f(e)
- (Backward edge) For $e \in E$ with f(e) > 0, create $e_{\text{reverse}} \in E_f$ with capacity f(e)

original flow network G





Flow Algorithm Idea

- Now we have a residual graph that lets us make forward progress or push back existing flow
- We will look for $s \leadsto t$ paths in G_f rather than G
- Once we have a path, we will "augment" flow along it similar to greedy
 - find bottleneck capacity edge on the path and push that much flow through it in $G_{\!f}$
- When we translate this back to G, this means:
 - We increment existing flow on a forward edge
 - Or we decrement flow on a backward edge

Augmenting Path & Flow

• An augmenting path P is a simple $s \sim t$ path in the residual graph G_f

Path that repeats no vertices

• The **bottleneck capacity** b of an augmenting path P is the minimum capacity of any edge in P.

Some $s \sim t$ path P in G_f

```
AUGMENT(f, P)
```

 $b \leftarrow$ bottleneck capacity of augmenting path P.

FOREACH edge $e \in P$:

IF $(e \in E, that is, e is forward edge)$

Increase f(e) in G by b

ELSE

Decrease f(e) in G by b

RETURN f.

If/else update flow in G, not G_f

Ford-Fulkerson Algorithm

- Start with f(e) = 0 for each edge $e \in E$
- Find a simple $s \leadsto t$ path P in the residual network $G_{\!f}$
- Augment flow along path P by bottleneck capacity b
- Repeat until you get stuck

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FORD—FULKERSON(G)

FOREACH edge e \in E: f(e) \leftarrow 0.

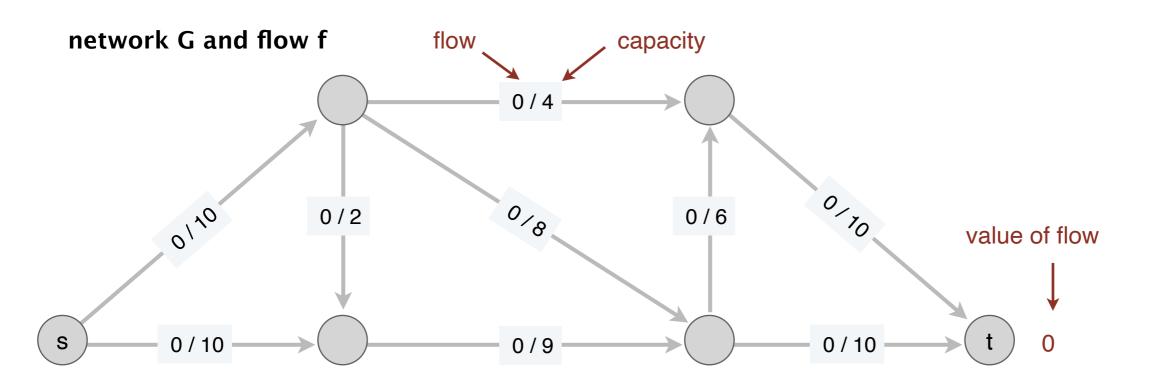
G_f \leftarrow residual network of G with respect to flow f.

WHILE (there exists an s \sim t path P in G_f)

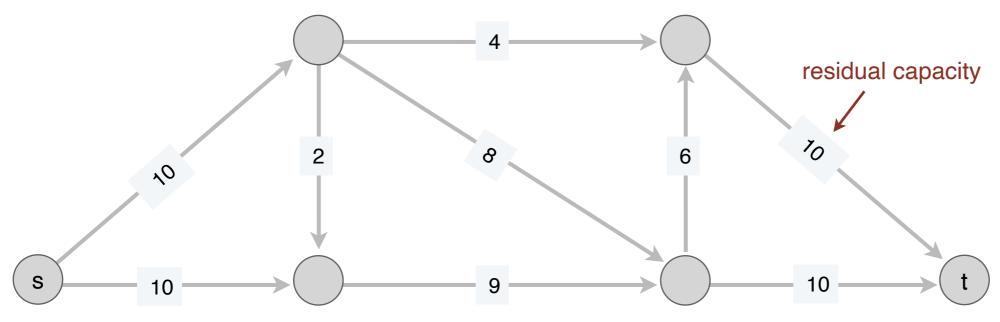
f \leftarrow \text{AUGMENT}(f, P).

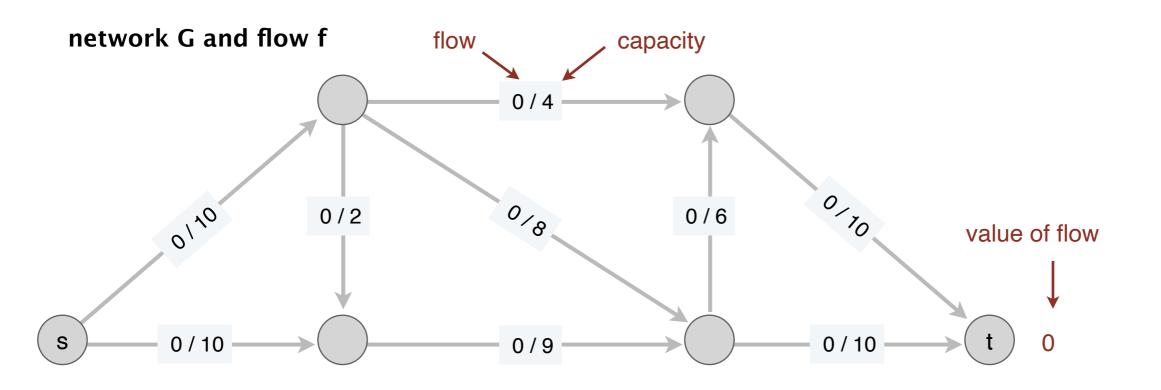
Update G_f.

RETURN f.
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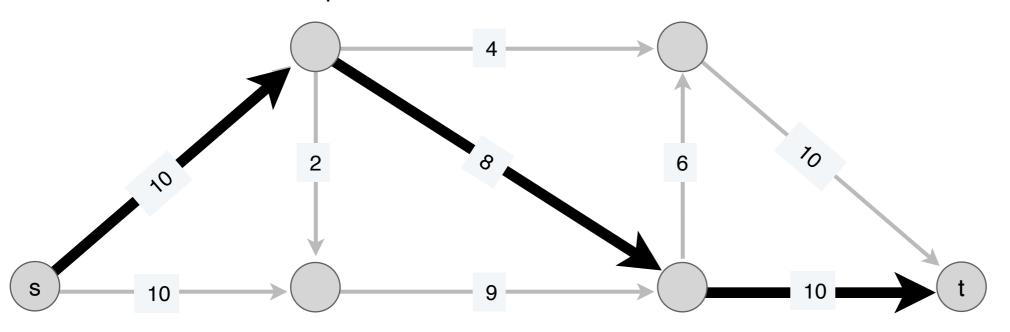


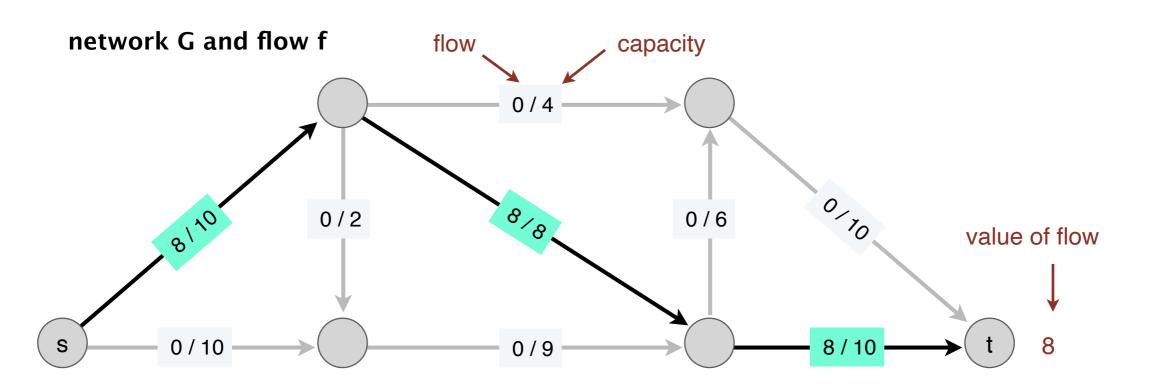
residual network Gf



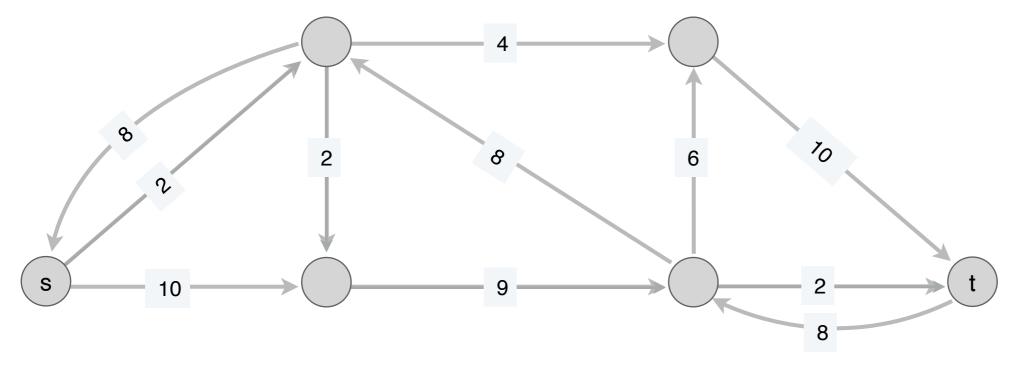


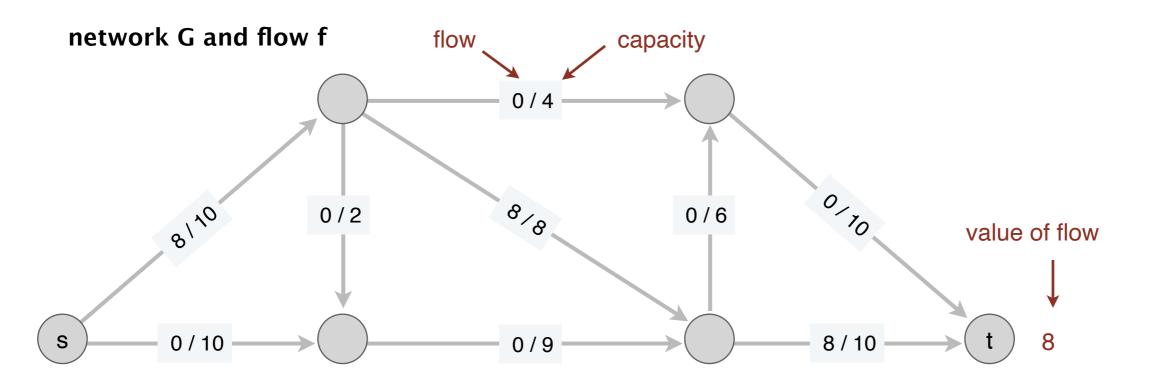
P in residual network Gf



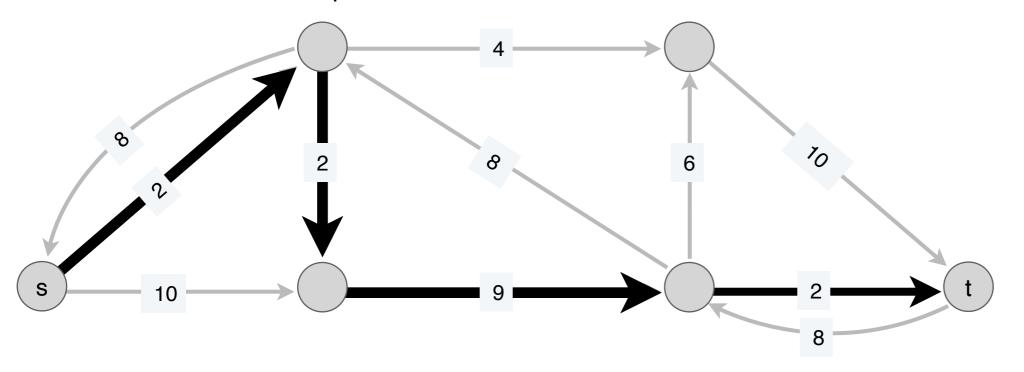


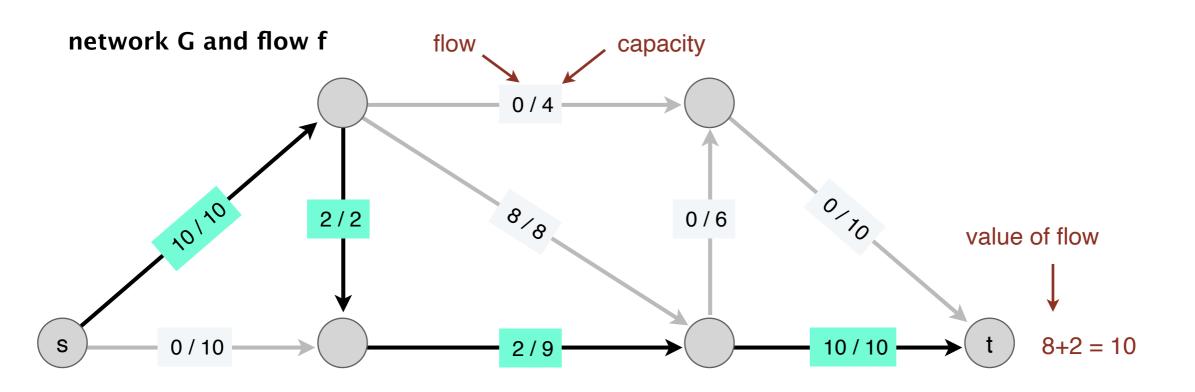
residual network Gf



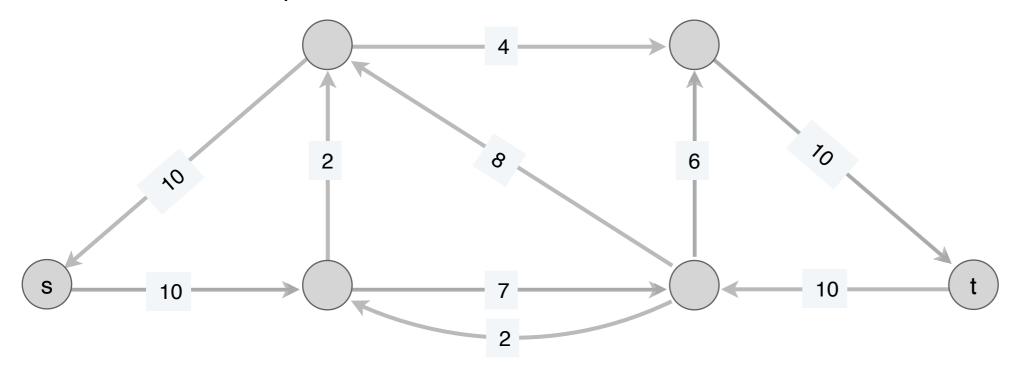


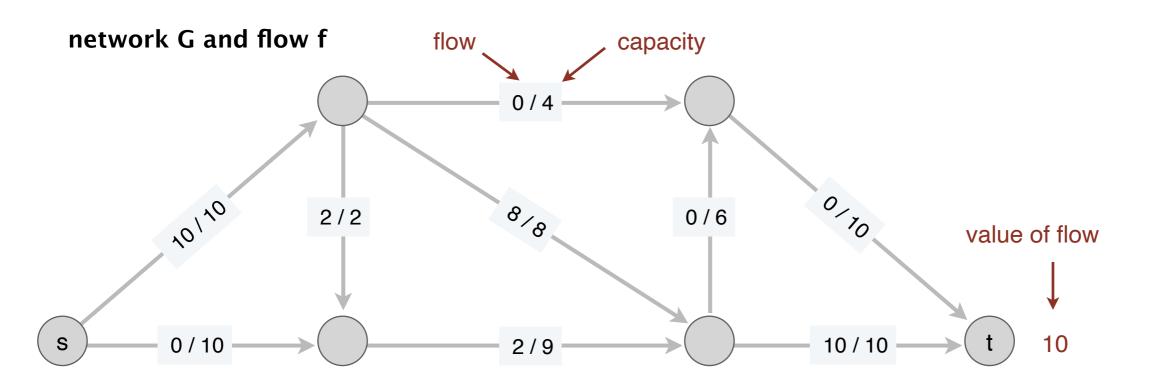
P in residual network Gf



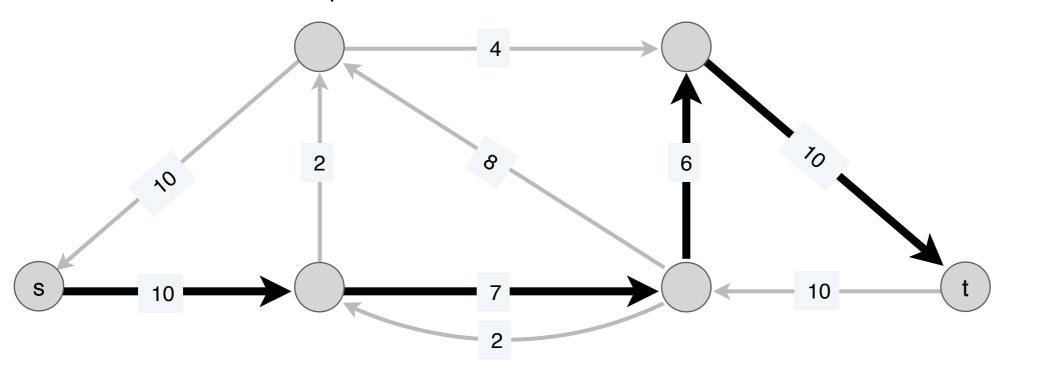


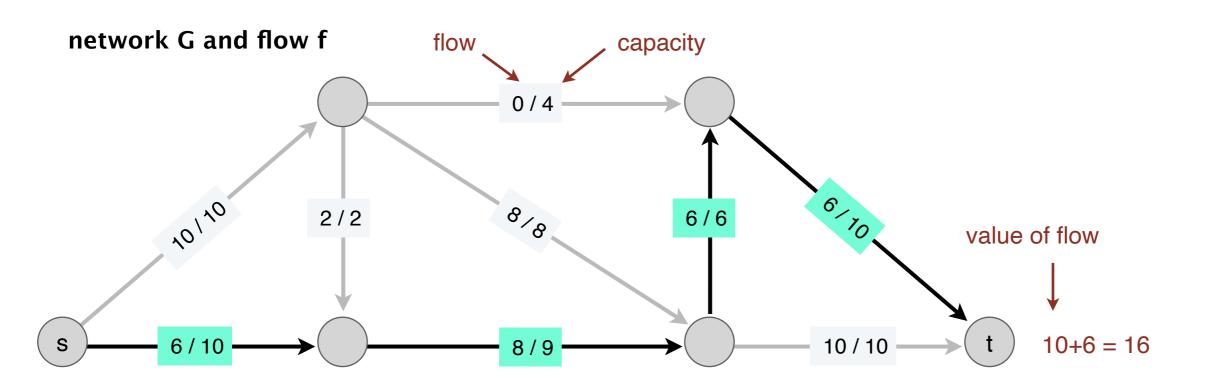
residual network Gf



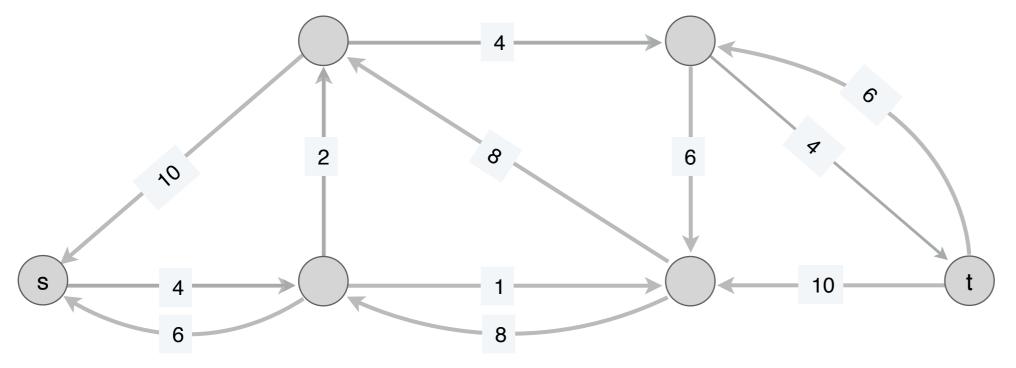


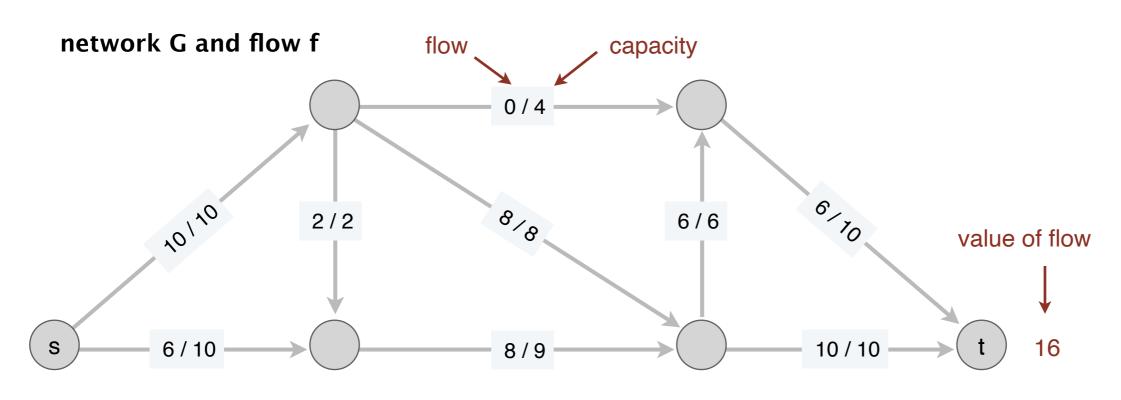
P in residual network Gf

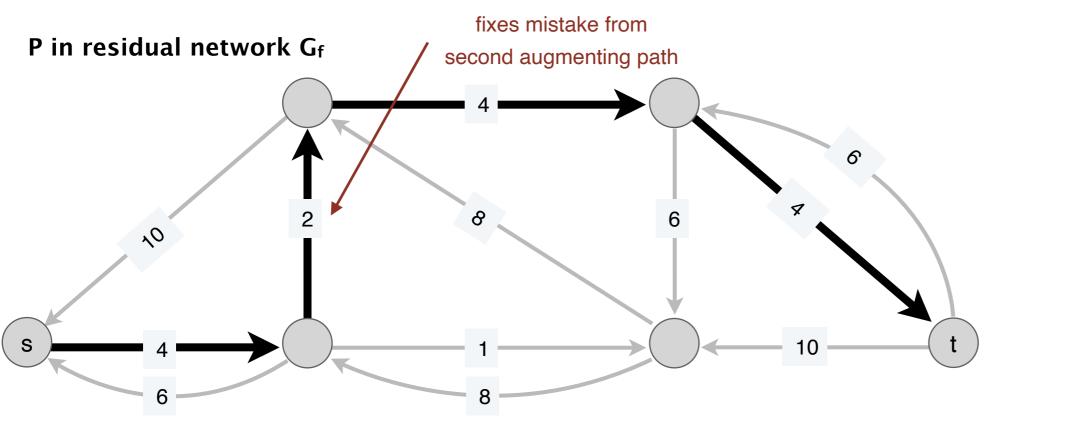


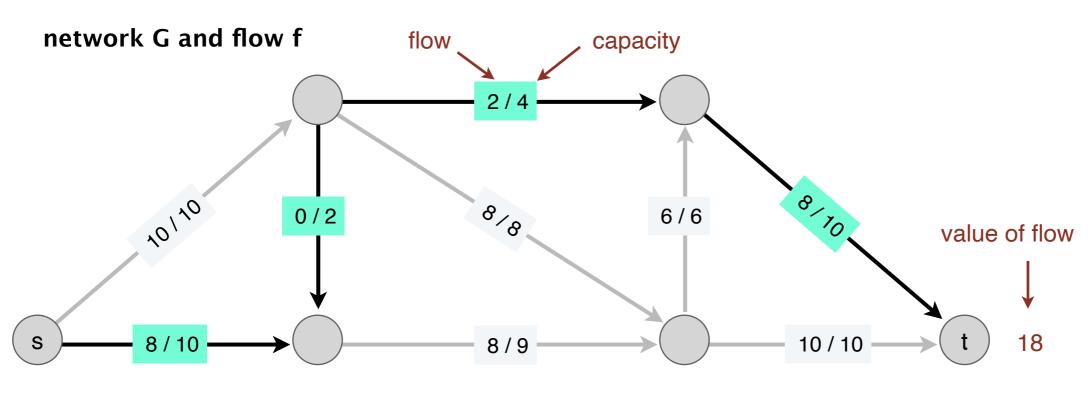


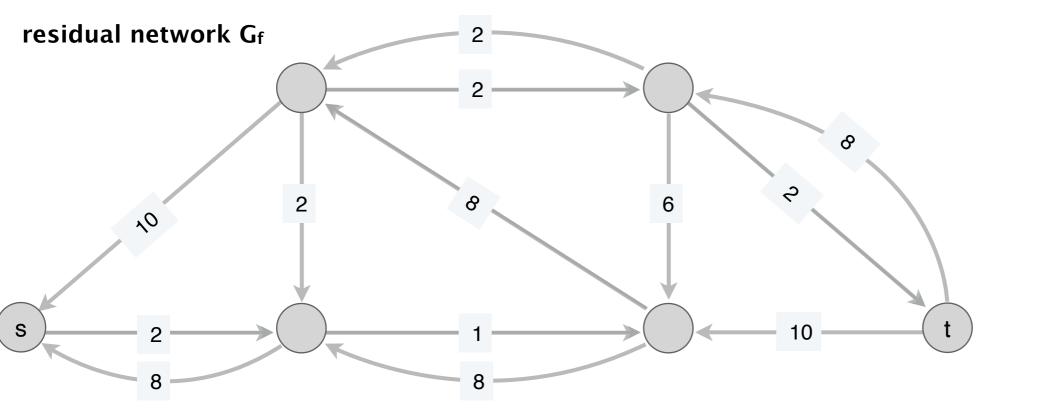
residual network Gf

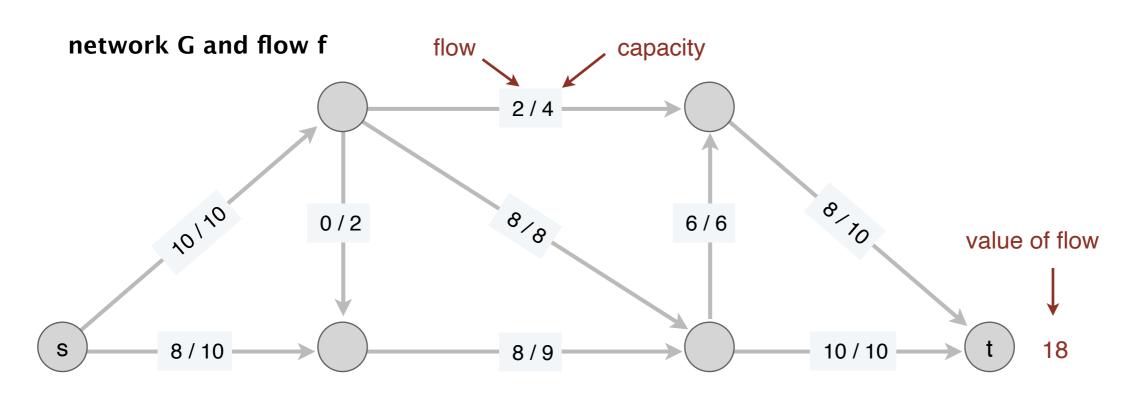


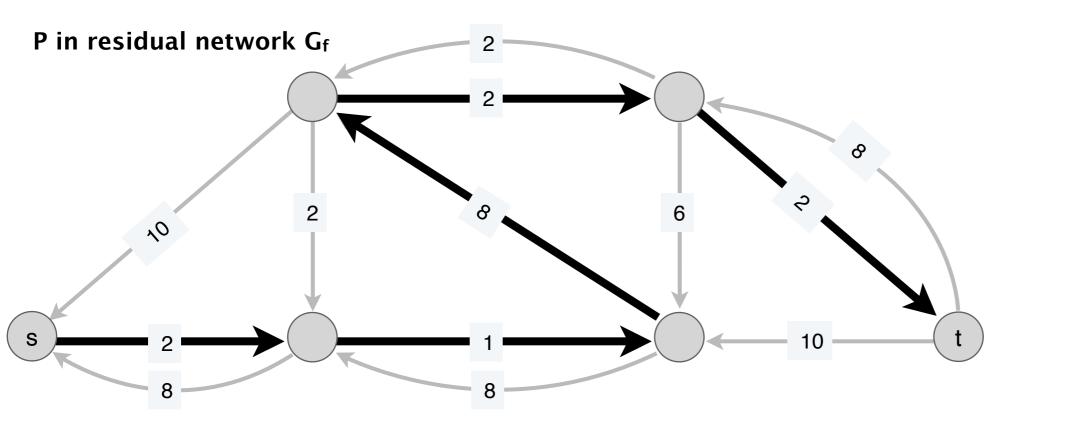


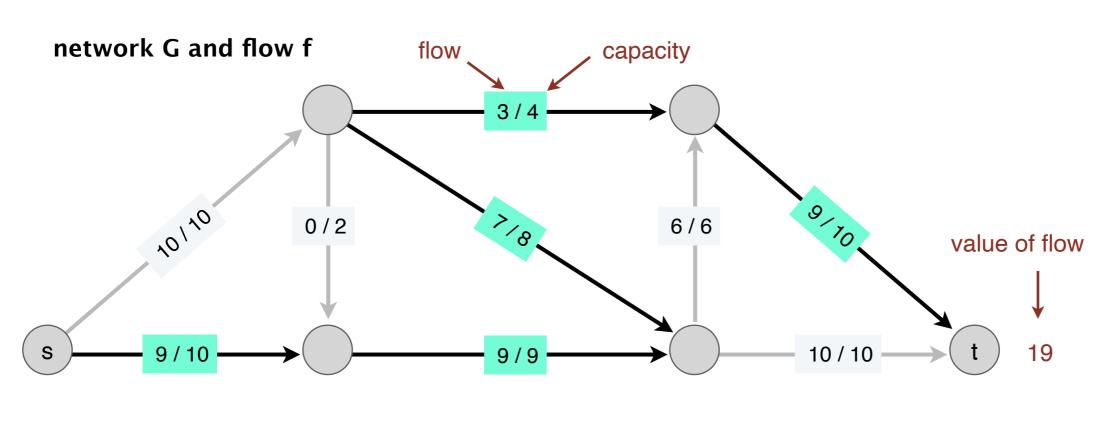


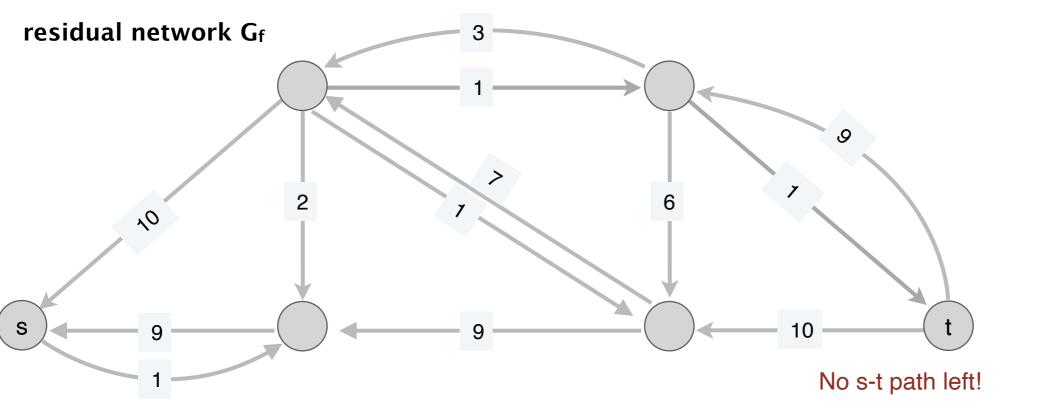


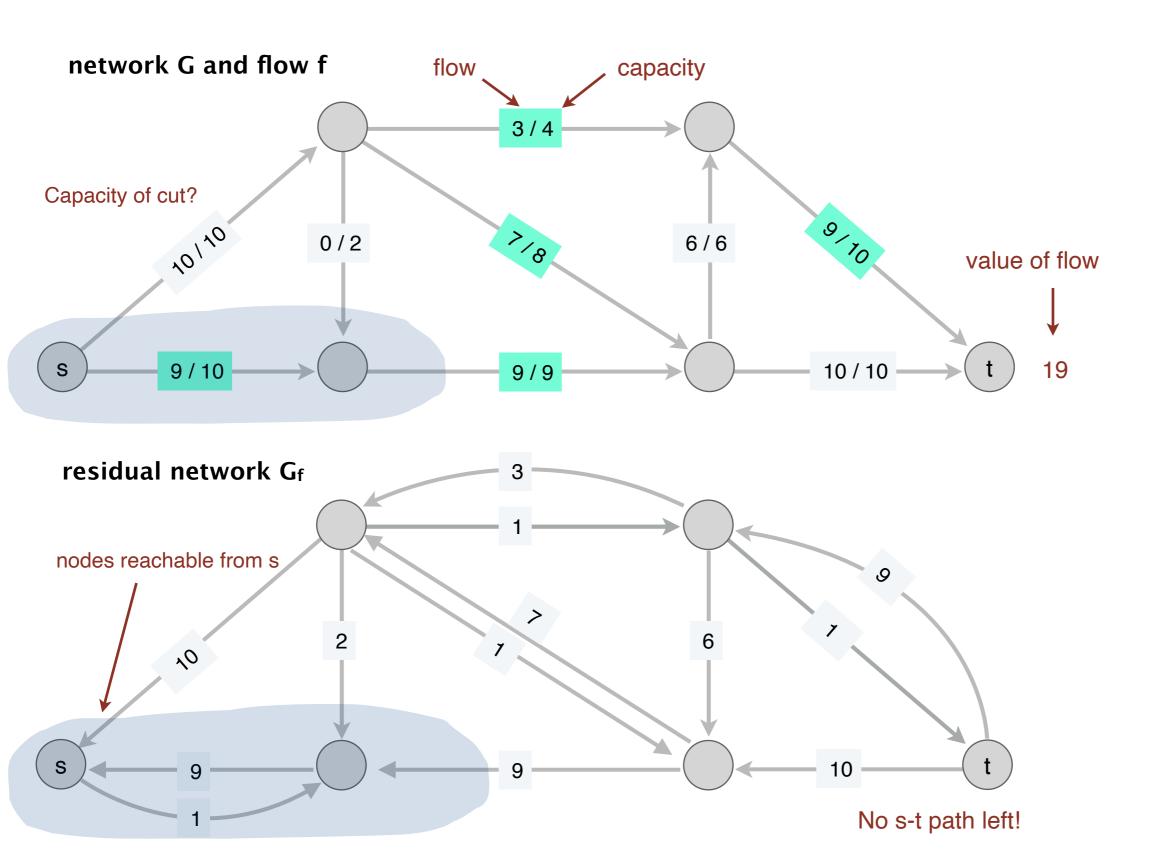












Analysis: Ford-Fulkerson

Analysis Outline

- Feasibility and value of flow:
 - Show that each time we update the flow, we are routing a feasible s-t flow through the network
 - And that value of this flow increases each time by that amount
- Optimality:
 - Final value of flow is the maximum possible
- Running time:
 - How long does it take for the algorithm to terminate?
- Space:
 - How much total space are we using?

Feasibility of Flow

- Claim. Let f be a feasible flow in G and let P be an augmenting path in G_f with bottleneck capacity b. Let $f' \leftarrow \mathsf{AUGMENT}(f,P)$, then f' is a feasible flow.
- **Proof**. Only need to verify constraints on the edges of P (since f' = f for other edges). Let $e = (u, v) \in P$
 - If e is a forward edge: f'(e) = f(e) + b $\leq f(e) + (c(e) - f(e)) = c(e)$
 - If e is a backward edge: f'(e) = f(e) b $\geq f(e) - f(e) = 0$
- Conservation constraint hold on any node in $u \in P$:
 - $f_{in}(u) = f_{out}(u)$, therefore $f'_{in}(u) = f'_{out}(u)$ for both cases

Value of Flow: Making Progress

• Claim. Let f be a feasible flow in G and let P be an augmenting path in G_f with bottleneck capacity b. Let $f' \leftarrow \mathsf{AUGMENT}(f,P)$, then v(f') = v(f) + b.

Proof.

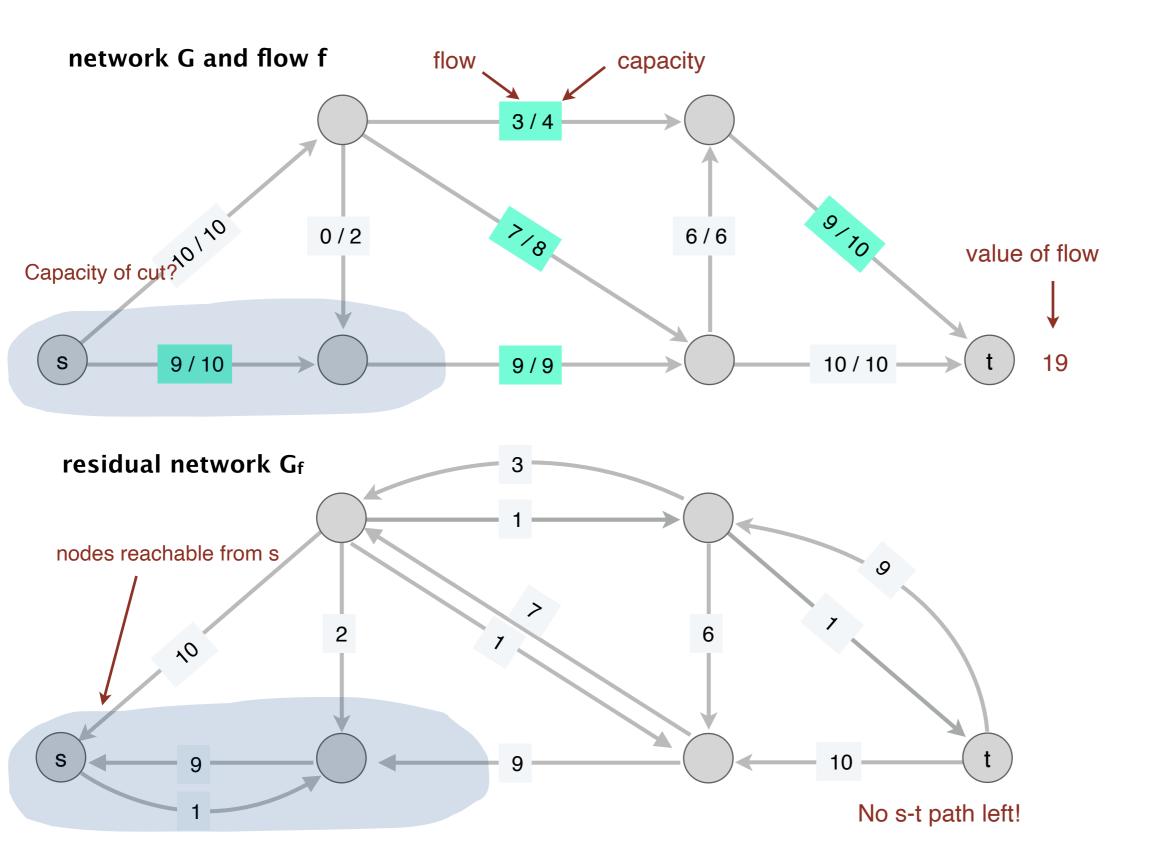
- First edge $e \in P$ must be out of s in G_f
- (P is simple so never visits s again)
- e must be a forward edge (P is a path from s to t)
- Thus f(e) increases by b, increasing v(f) by $b \blacksquare$
- Note. Means the algorithm makes forward progress each time!

Optimality

- Recall: If f is any feasible s-t flow and (S,T) is any s-t cut then $v(f) \le c(S,T)$.
- We will show that the Ford-Fulkerson algorithm terminates in a flow that achieves optimality, that is,
- Ford-Fulkerson finds a flow f^* and there exists a cut (S^*, T^*) such that, $v(f^*) = c(S^*, T^*)$
- Proving this shows that it finds the maximum flow (and the min cut)
- This also proves the max-flow min-cut theorem

- **Lemma**. Let f be an s-t flow in G such that there is no augmenting path in the residual graph G_f , then there exists a cut (S^*, T^*) such that $v(f) = c(S^*, T^*)$.
- Proof.
- Let $S^* = \{v \mid v \text{ is reachable from } s \text{ in } G_f\}$, $T^* = V S^*$
- Is this an *s-t* cut?
 - $s \in S, t \in T, S \cup T = V$ and $S \cap T = \emptyset$
- Consider an edge $e = u \rightarrow v$ with $u \in S^*, v \in T^*$, then what can we say about f(e)?

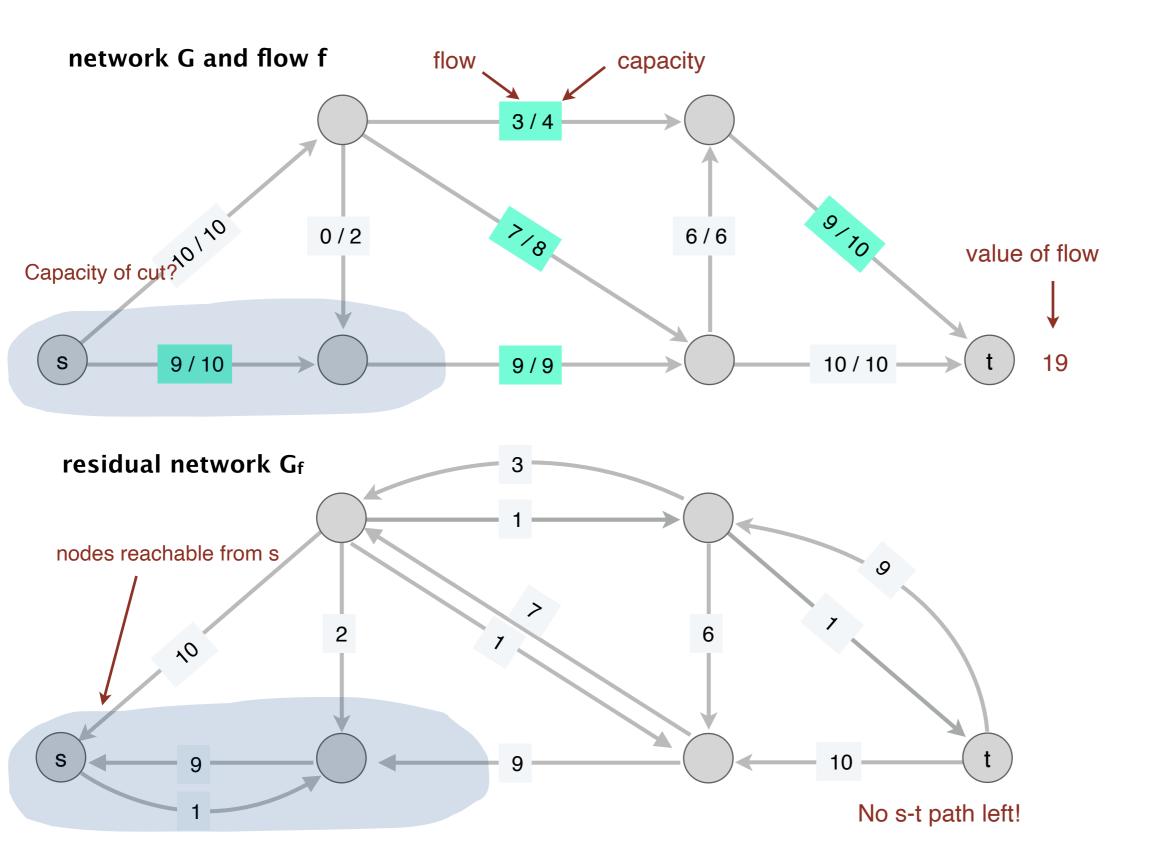
Recall: Ford-Fulkerson Example



- **Lemma**. Let f be a s-t flow in G such that there is no augmenting path in the residual graph G_f , then there exists a cut (S^*, T^*) such that $v(f) = c(S^*, T^*)$.
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- Consider an edge $e = u \rightarrow v$ with $u \in S^*, v \in T^*$, then what can we say about f(e)?
 - f(e) = c(e)

- **Lemma**. Let f be a s-t flow in G such that there is no augmenting path in the residual graph G_f , then there exists a cut (S^*, T^*) such that $v(f) = c(S^*, T^*)$.
- Proof. (Cont.)
- Let $S^* = \{v \mid v \text{ is reachable from } s \text{ in } G_f\}$, $T^* = V S^*$
- Is this an *s-t* cut?
 - $s \in S, t \in T, S \cup T = V$ and $S \cap T = \emptyset$
- Consider an edge $e = w \rightarrow v$ with $v \in S^*, w \in T^*$, then what can we say about f(e)?

Recall: Ford-Fulkerson Example



- **Lemma**. Let f be a s-t flow in G such that there is no augmenting path in the residual graph G_f , then there exists a cut (S^*, T^*) such that $v(f) = c(S^*, T^*)$.
- Proof. (Cont.)
- Let $S^* = \{v \mid v \text{ is reachable from } s \text{ in } G_f\}$, $T^* = V S^*$
- Is this an *s-t* cut?
 - $s \in S, t \in T, S \cup T = V$ and $S \cap T = \emptyset$
- Consider an edge $e = w \to v$ with $v \in S^*, w \in T^*$, then what can we say about f(e)?
 - f(e) = 0

Otherwise, there would have been a backwards edge in the residual graph

- **Lemma**. Let f be a s-t flow in G such that there is no augmenting path in the residual graph G_f , then there exists a cut (S^*, T^*) such that $v(f) = c(S^*, T^*)$.
- Proof. (Cont.)
- Let $S^* = \{v \mid v \text{ is reachable from } s \text{ in } G_f\}$, $T^* = V S^*$
- Thus, all edges leaving S^{*} are completely saturated and all edges entering S^{*} have zero flow
- $v(f) = f_{out}(S^*) f_{in}(S^*) = f_{out}(S^*) = c(S^*, T^*) \blacksquare$
- Corollary. Ford-Fulkerson returns the maximum flow.

Ford-Fulkerson Algorithm Running Time

Ford-Fulkerson Performance

```
FORD—FULKERSON(G)

FOREACH edge e \in E : f(e) \leftarrow 0.

G_f \leftarrow residual network of G with respect to flow f.

WHILE (there exists an s\simt path P in G_f)

f \leftarrow \text{AUGMENT}(f, P).

Update G_f.

RETURN f.
```

- Does the algorithm terminate?
- Can we bound the number of iterations it does?
- Running time?

Ford-Fulkerson Running Time

- Recall we proved that with each call to AUGMENT, we increase value of flow by $b={\rm bottleneck}(G_f,P)$
- **Assumption**. Suppose all capacities c(e) are integers.
- Integrality invariant. Throughout Ford–Fulkerson, every edge flow f(e) and corresponding residual capacity is an integer. Thus $b \ge 1$.
- Let $C = \max_{u} c(s \to u)$ be the maximum capacity among edges leaving the source s.
- It must be that $v(f) \le (n-1)C$
- Since, v(f) increases by $b \ge 1$ in each iteration, it follows that FF algorithm terminates in at most v(f) = O(nC) iterations.

Ford-Fulkerson Performance

```
FORD—FULKERSON(G)

FOREACH edge e \in E : f(e) \leftarrow 0.

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WHILE (there exists an s \sim t path P in G_f)

f \leftarrow \text{AUGMENT}(f, P).

Update G_f.

RETURN f.
```

- Operations in each iteration?
 - Find an augmenting path in $G_{\!f}$
 - Augment flow on path
 - Update G_f

Ford-Fulkerson Running Time

- Claim. Ford-Fulkerson can be implemented to run in time O(nmC), where $m = |E| \ge n 1$ and $C = \max_{u} c(s \to u)$.
- Proof. Time taken by each iteration:
- Finding an augmenting path in G_f
 - G_f has at most 2m edges, using BFS/DFS takes $O(m+n) = O(m) \ {\rm time}$
- Augmenting flow in P takes O(n) time
- Given new flow, we can build new residual graph in O(m) time
- Overall, O(m) time per iteration

Acknowledgments

- Some of the material in these slides are taken from
 - Kleinberg Tardos Slides by Kevin Wayne (https://www.cs.princeton.edu/~wayne/kleinberg-tardos/pdf/04GreedyAlgorithmsl.pdf)
 - Jeff Erickson's Algorithms Book (http://jeffe.cs.illinois.edu/ teaching/algorithms/book/Algorithms-JeffE.pdf)
 - Shikha Singh