Flow Networks: Max Flow = Min Cut

Admin

- No pending problem set
 - I will hand out an activity that I encourage you use for practice
 - (Most) TA hours will still be held this weekend
 - Ask TAs any questions about the course
 - Ask TAs about the activity (Ford-Fulkerson Algorithm)
- Questions about pre-registration?
- Lab usage?

Relationship between Flows and Cuts

Recall: Cut Capacity

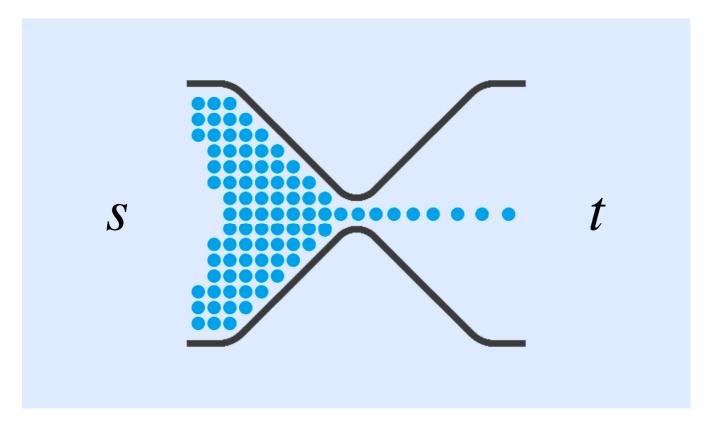
Recall. A cut (S, T) in a graph is a partition of vertices such that $S \cup T = V$, $S \cap T = \emptyset$ and S, T are non-empty.

- **Definition**. An (s, t)-*cut* is a cut (S, T) s.t. $s \in S$ and $t \in T$.
- Capacity of a (s, t)-cut (S, T) is the sum of the capacities of edges leaving S:

$$c(S,T) = \sum_{v \in S, w \in T} c(v \to w)$$

Recall: Flows and Cuts

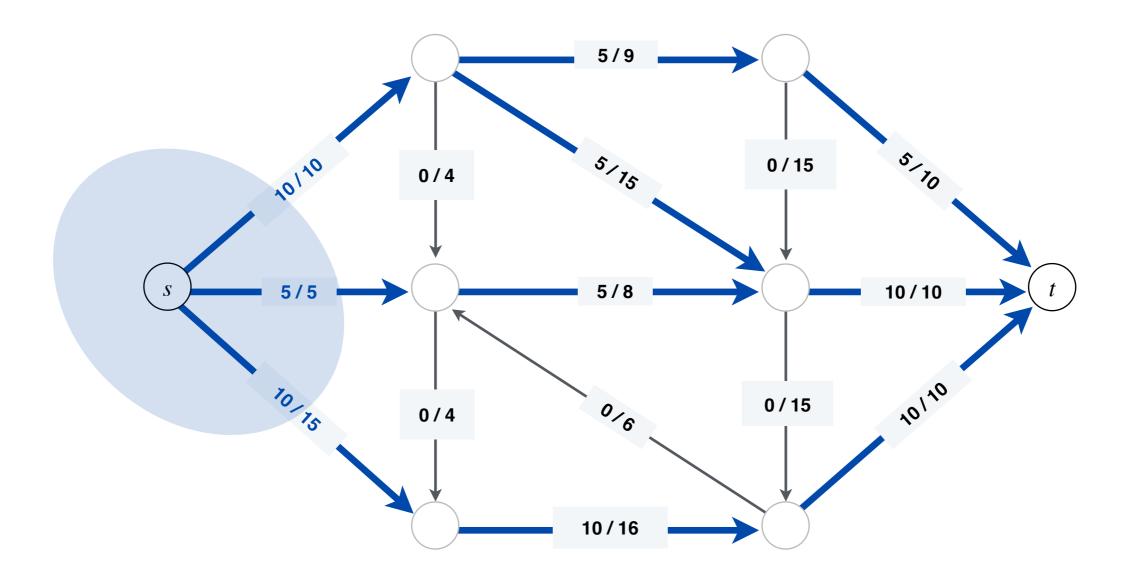
- Cuts represent "bottlenecks" in a flow network
- For any (s, t)-cut, all flow needs to "exit" S to get to t



• We will now formalize this intuition

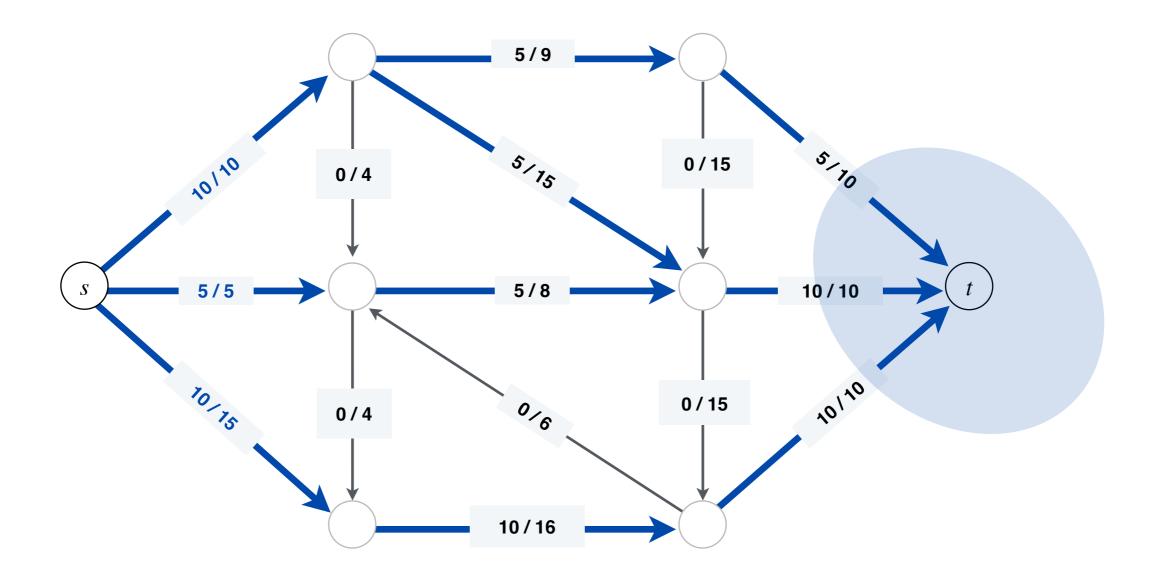
Claim. Let *f* be any *s*-*t* flow and (S, T) be any *s*-*t* cut then $v(f) \le c(S, T)$

• There are two *s*-*t* cuts for which this is easy to see (which ones?)



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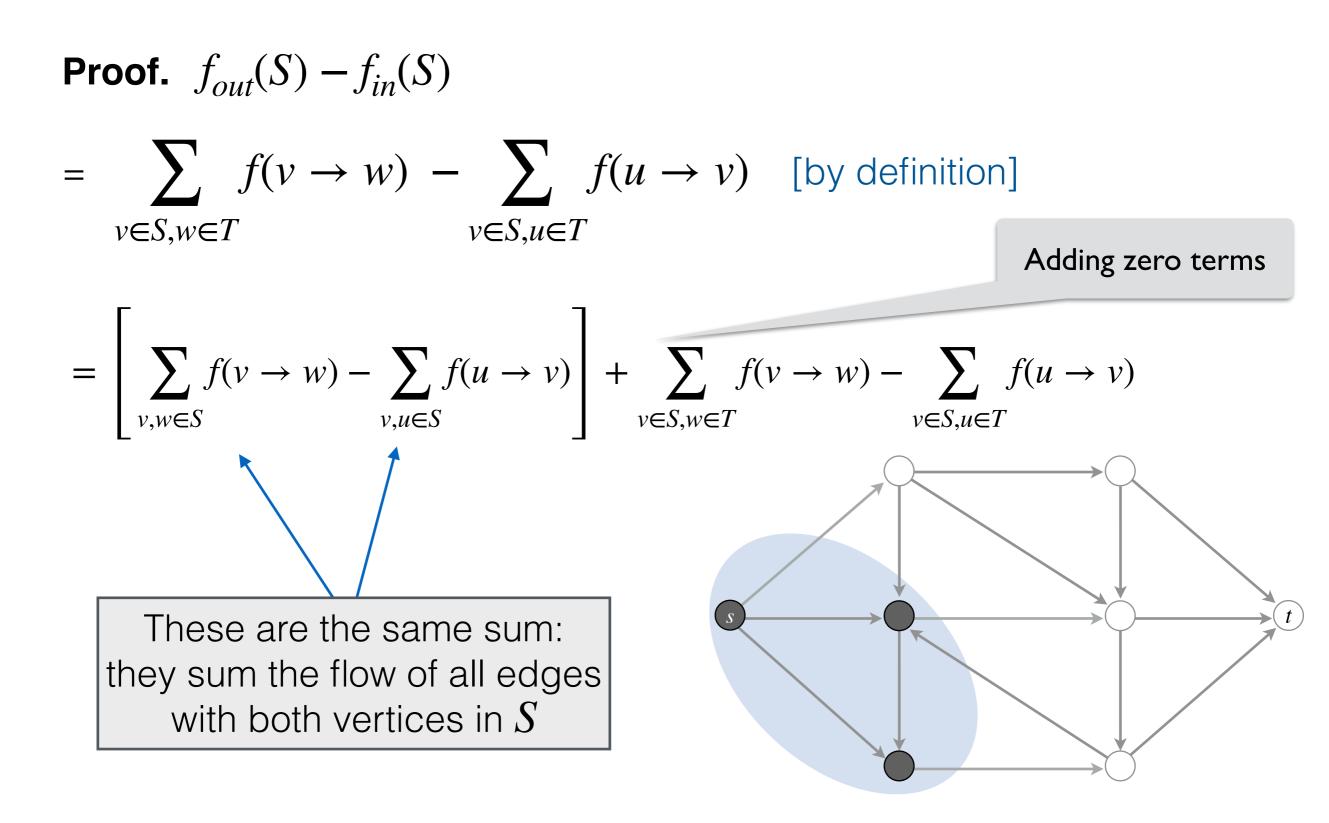
To prove this for any cut, we first relate the flow value in a network to the **net flow** leaving a cut

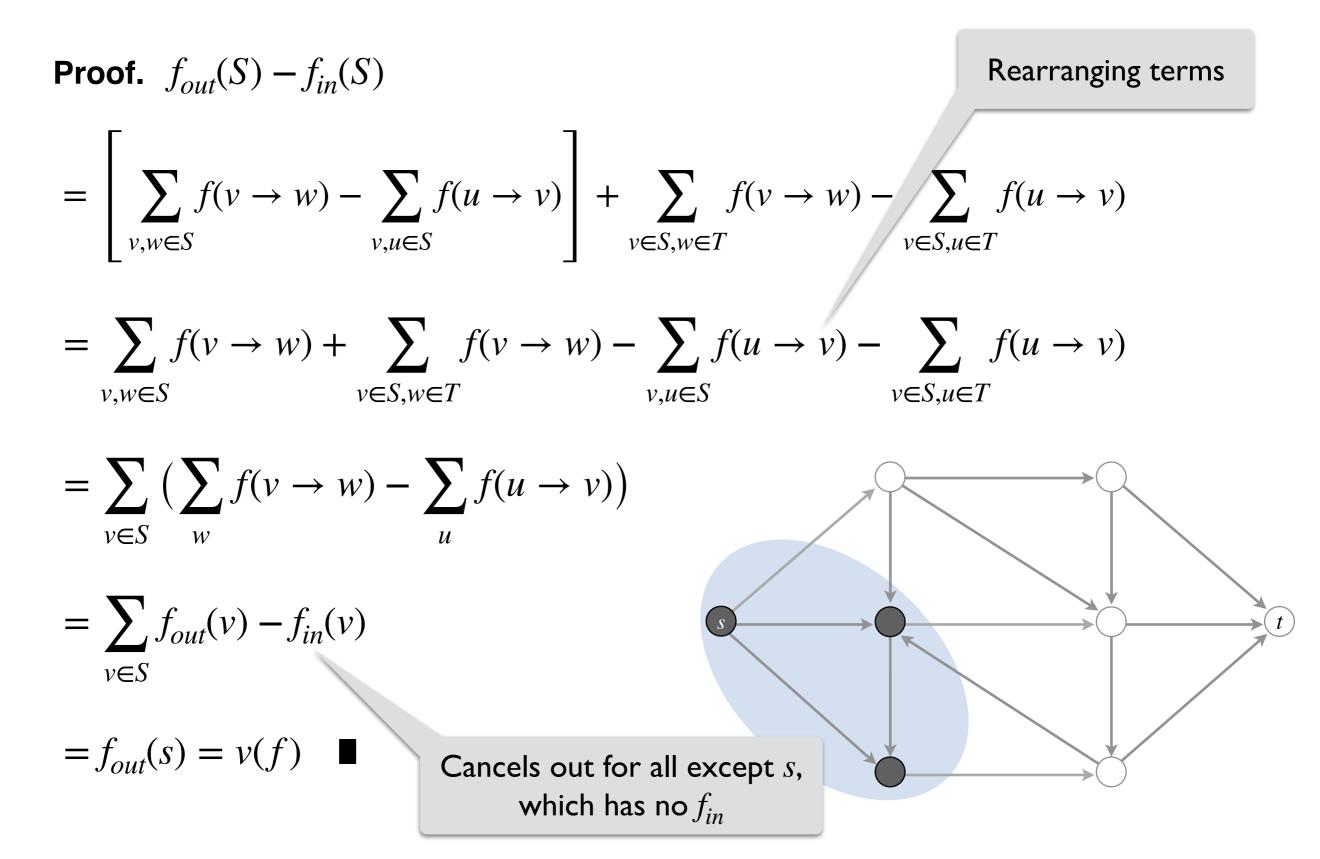
• Lemma. For any feasible (s, t)-flow f on G = (V, E) and any (s, t)-cut, $v(f) = f_{out}(S) - f_{in}(S)$, where

•
$$f_{out}(S) = \sum_{v \in S, w \in T} f(v \to w)$$
 (sum of flow 'leaving' S)

•
$$f_{in}(S) = \sum_{v \in S, w \in T} f(w \to v)$$
 (sum of flow 'entering' S)

• Note: $f_{out}(S) = f_{in}(T)$ and $f_{in}(S) = f_{out}(T)$





- We use this result to prove that the value of a flow cannot exceed the capacity of any cut in the network.
- Claim. Let f be any s-t flow and (S, T) be any s-t cut then $v(f) \le c(S, T)$ Sum of capacities leaving S

• **Proof.**
$$v(f) = f_{out}(S) - f_{in}(S)$$

$$\leq f_{out}(S) = \sum_{v \in S, w \in T} f(v \to w) \qquad \text{When is } v(f) = c(S, T)?$$
$$\leq \sum_{v \in S, w \in T} c(v, w) = c(S, T) \qquad f_{in}(S) = 0, f_{out}(S) = c(S, T)$$

Max-Flow & Min-Cut

- Suppose the c_{\min} is the capacity of the **minimum cut** in a network
- What can we say about the feasible flow we can send through it
 - cannot be more than c_{\min}
- In fact, whenever we find any *s*-*t* flow *f* and any *s*-*t* cut (*S*, *T*) such that, v(f) = c(S, T) we can conclude that:
 - f is the maximum flow, and,
 - (S, T) is the minimum cut
- The question now is, given any flow network with min cut c_{\min} , is it always possible to route a feasible *s*-*t* flow *f* with $v(f) = c_{\min}$

Max-Flow Min-Cut Theorem

There is a beautiful, powerful relationship between these two problems in given by the following theorem.

• **Theorem**. Given any flow network G, there exists a feasible (s, t)-flow f and an (s, t)-cut (S, T) such that,

v(f) = c(S, T)

- Informally, in a flow network, the max-flow = min-cut
- This will guide our algorithm design for finding max flow
- (Will prove this theorem by construction in a bit.)

Network Flow History

- In 1950s, US military researchers Harris and Ross wrote a classified report about the rail network linking Soviet Union and Eastern Europe
 - Vertices were the geographic regions
 - Edges were railway links between the regions
 - Edge weights were the rate at which material could be shipped from one region to next
- Ross and Harris determined:
 - Maximum amount of stuff that could be moved from Russia to Europe (max flow)
 - Cheapest way to disrupt the network by removing rail links (min cut)

Network Flow History

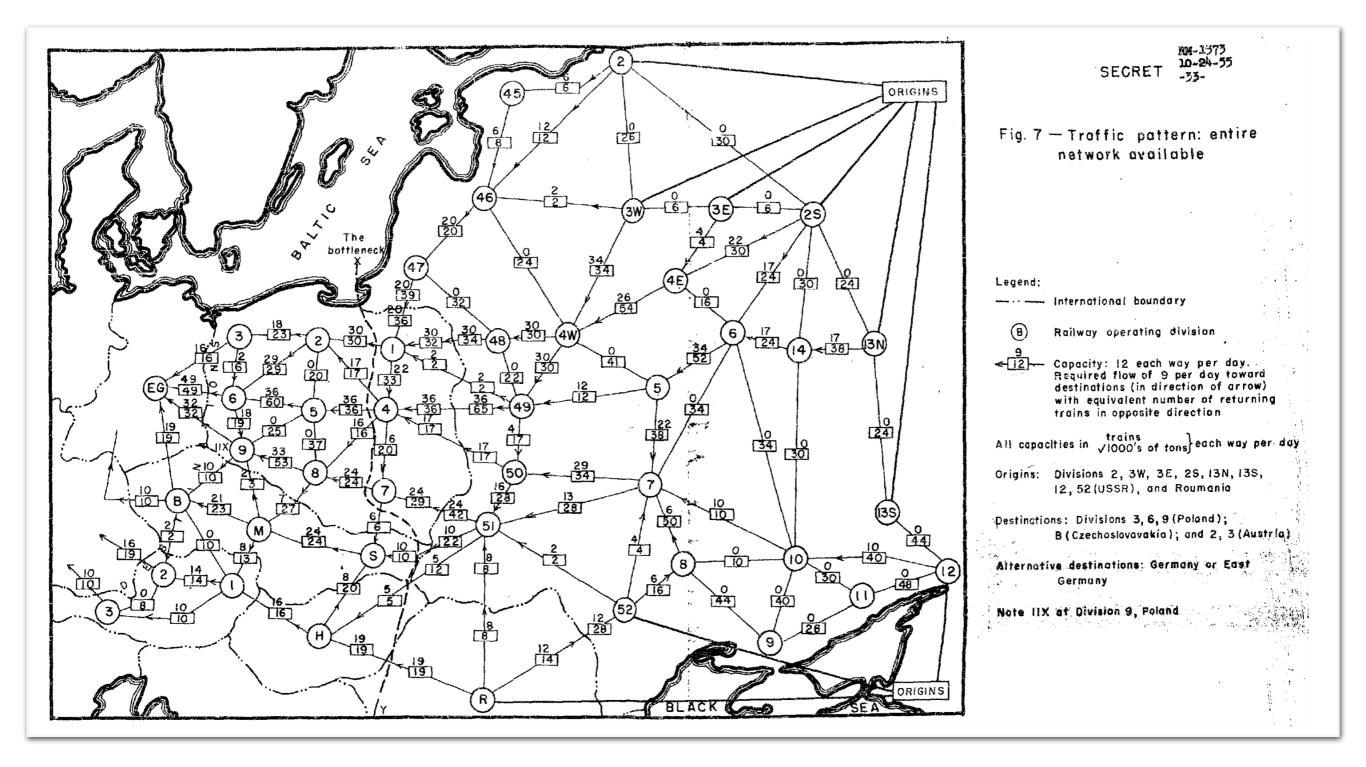


Image Credits: — Jeff Erickson's book and T[homas] E. Harris and F[rank] S. Ross. Fundamentals of a method for evaluating rail net capacities. The RAND Corporation, Research Memorandum RM-1517, October 24, 1955. United States Government work in the public domain. http://www.dtic.mil/dtic/tr/fulltext/u2/093458.pdf

Ford-Fulkerson Algorithm

We will design a max-flow algorithm and show that there is a s-t cut s.t. value of flow computed by algorithm = capacity of cut

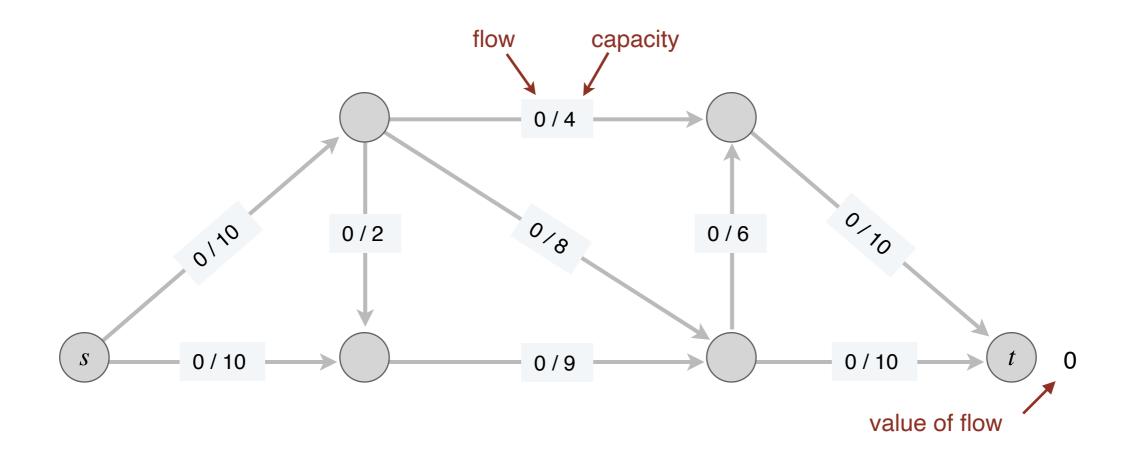
- Let's start with a greedy approach:
 - Pick an *s*-*t* path and push as much flow as possible down it
 - Repeat until you get stuck

Note: This won't actually work, but it gives us a sense of what we need to keep track of to improve it

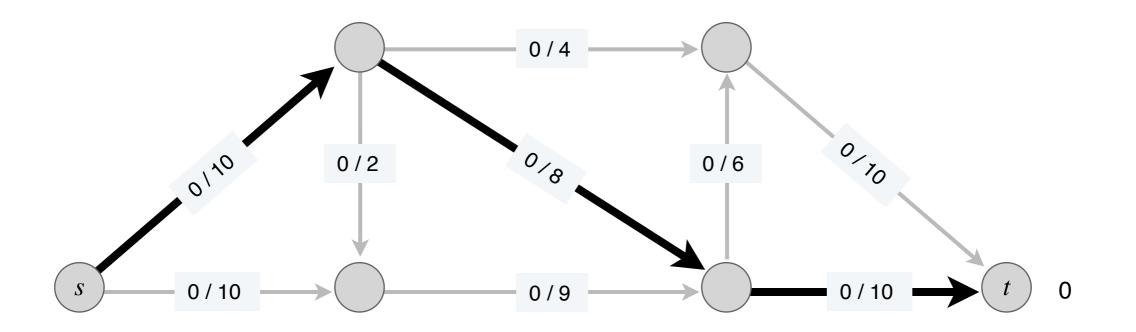
Greedy strategy:

- Start with f(e) = 0 for each edge
- Find an $s \sim t$ path P where each edge has f(e) < c(e)
- "Augment" flow (as much as possible) along path ${\it P}$
- Repeat until you get stuck
- Let's explore an example

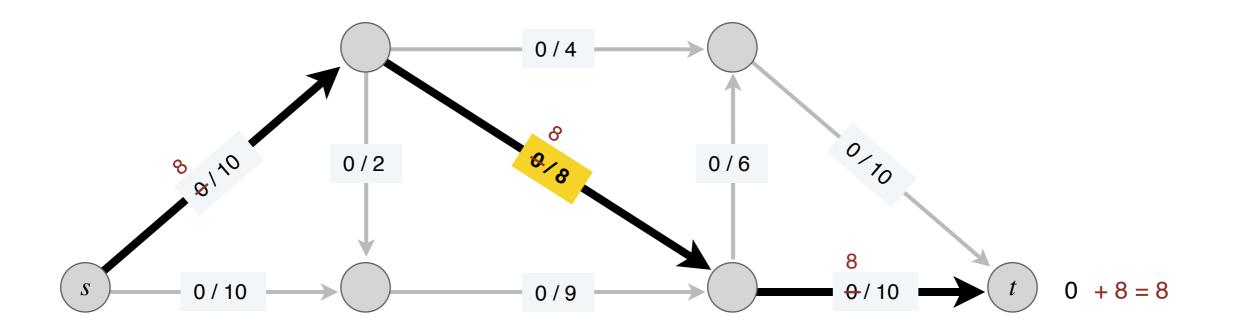
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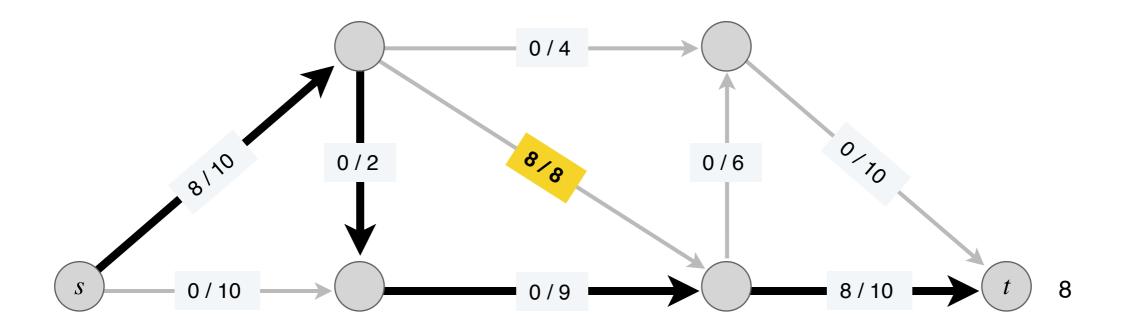
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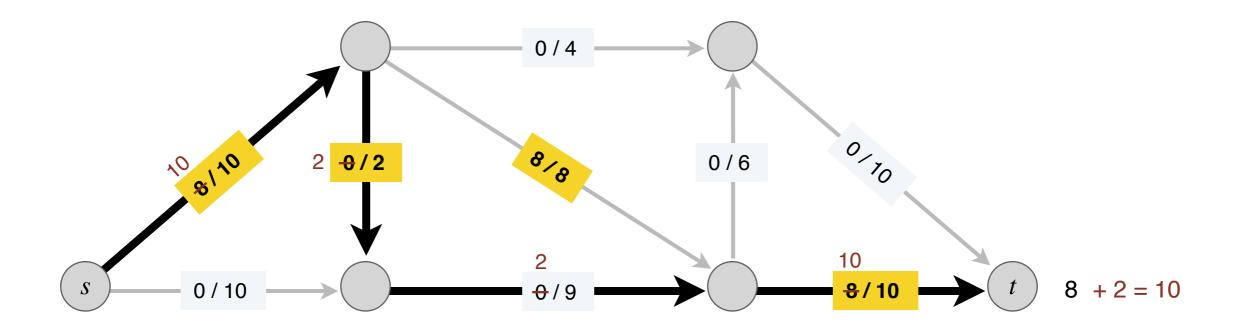
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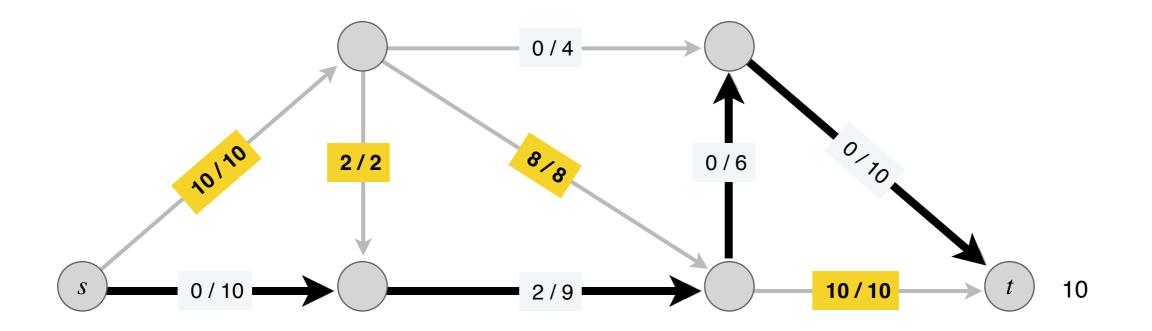
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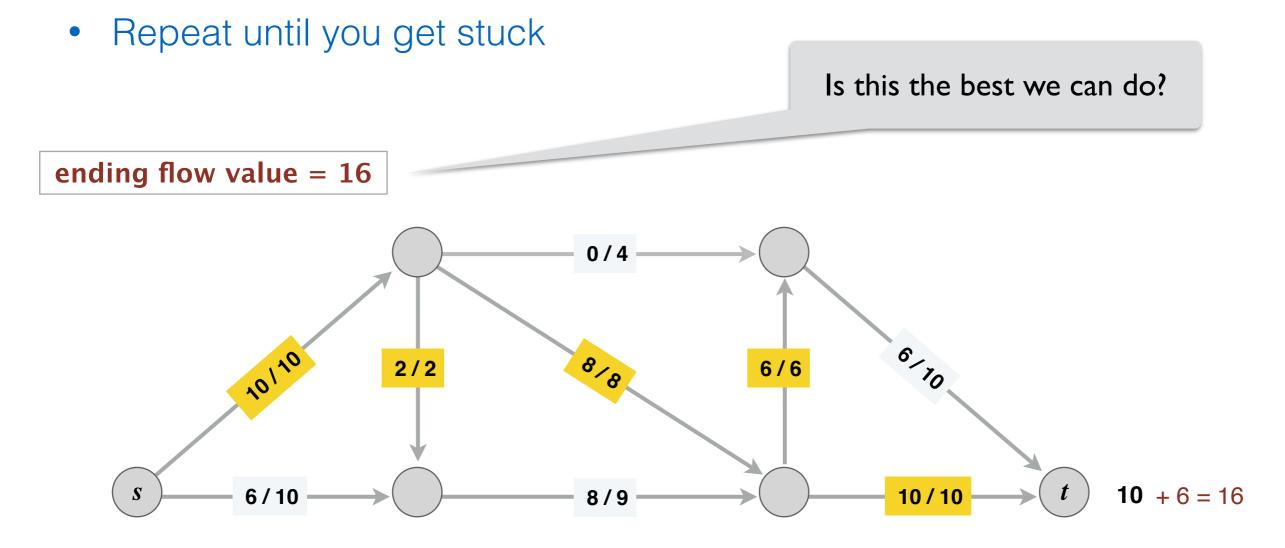
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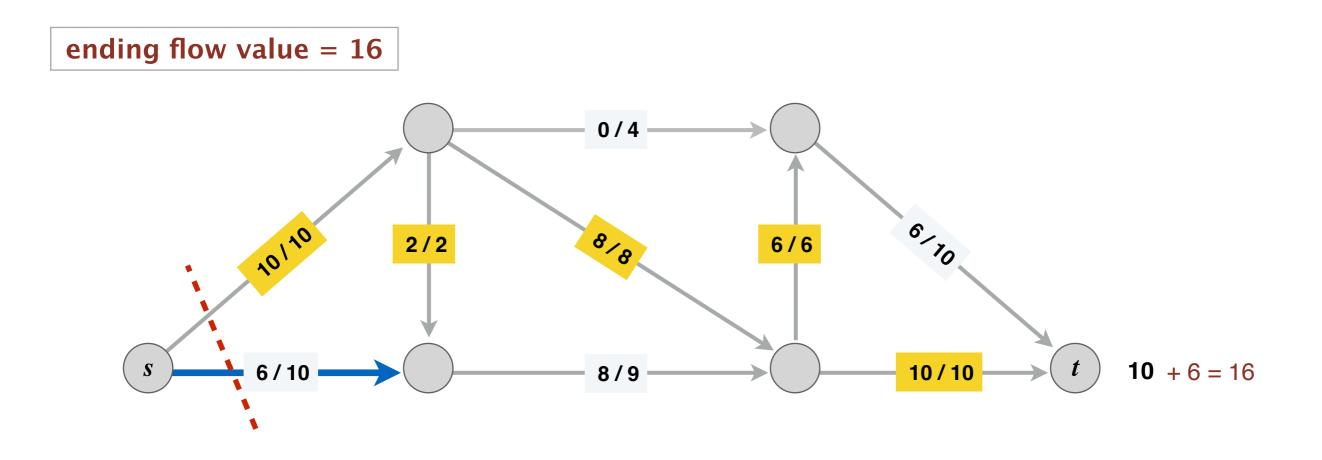
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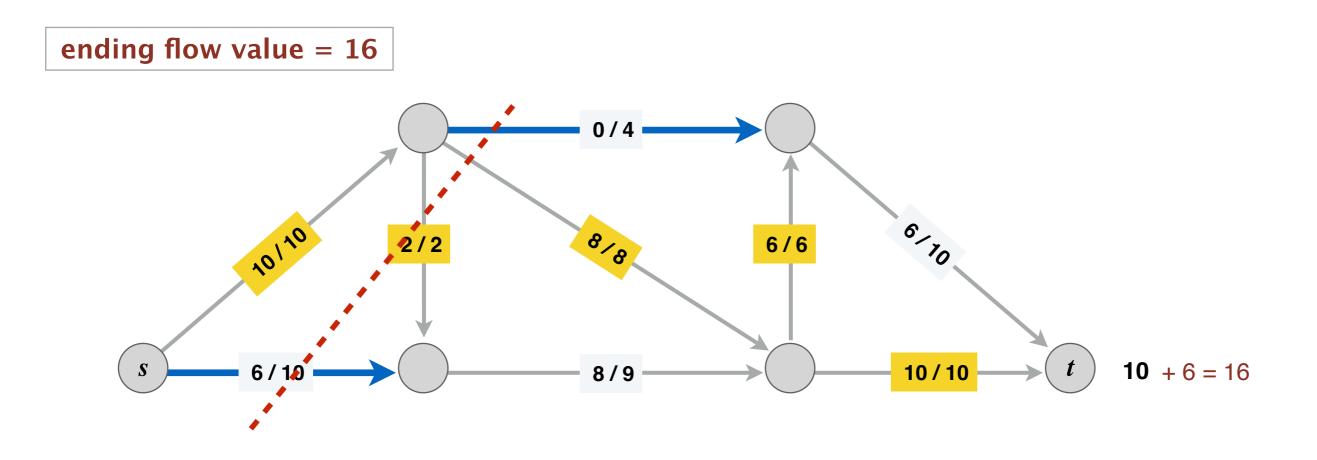
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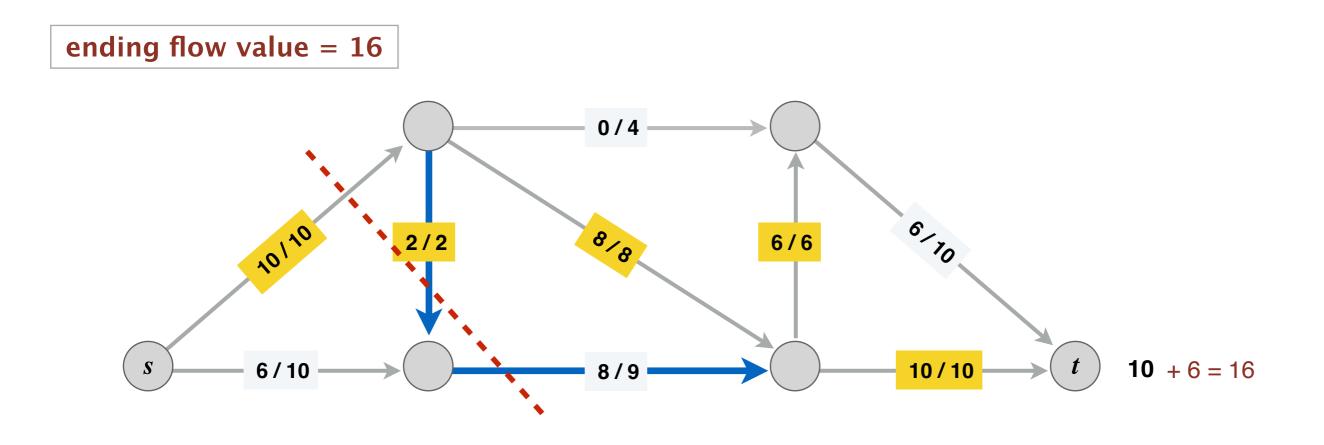
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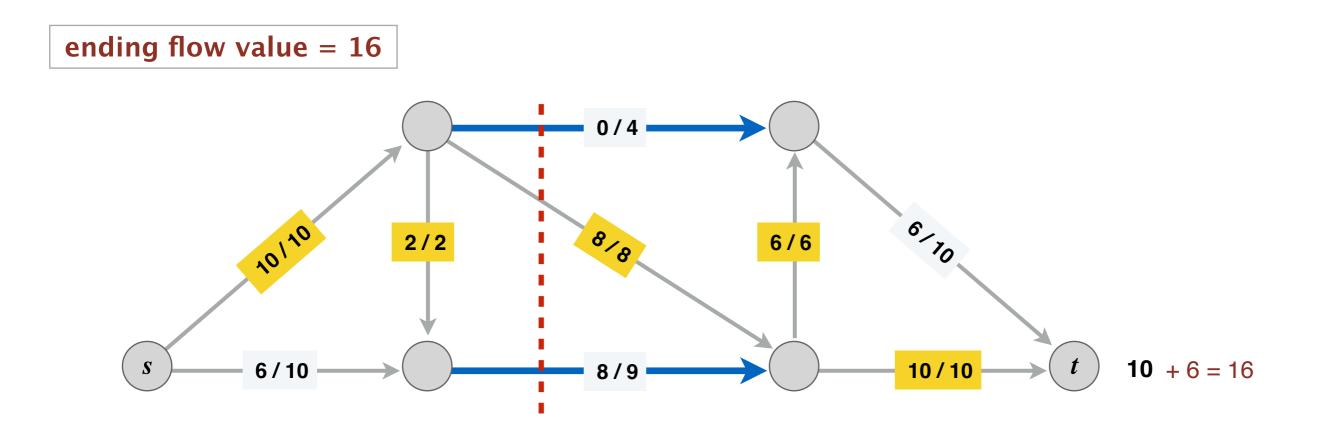
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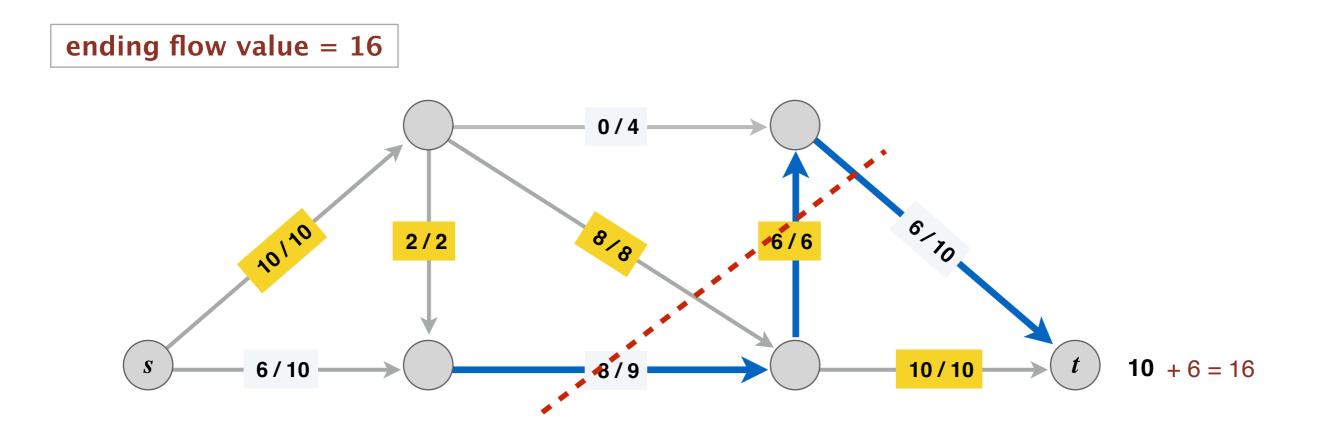
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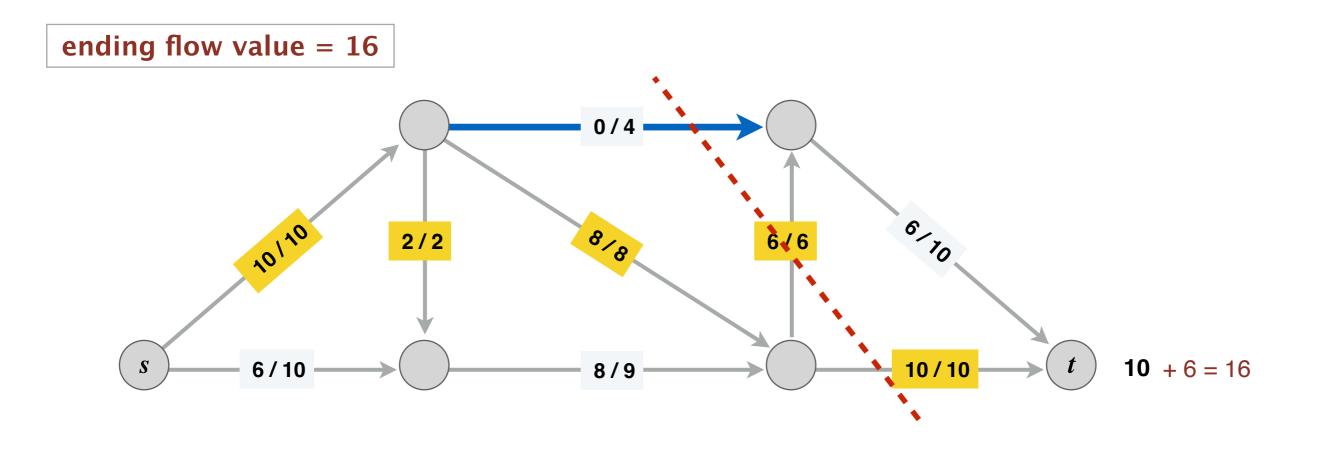
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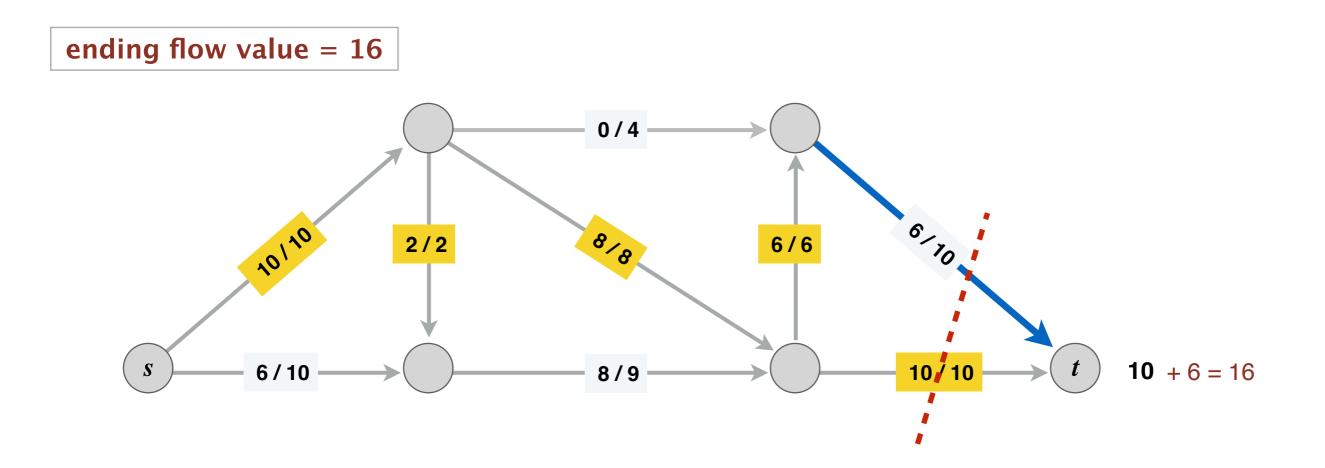
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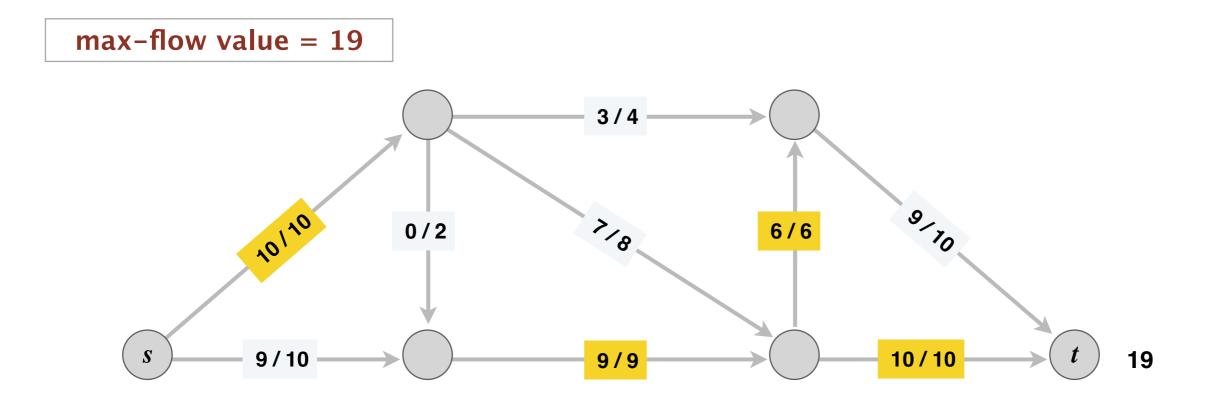
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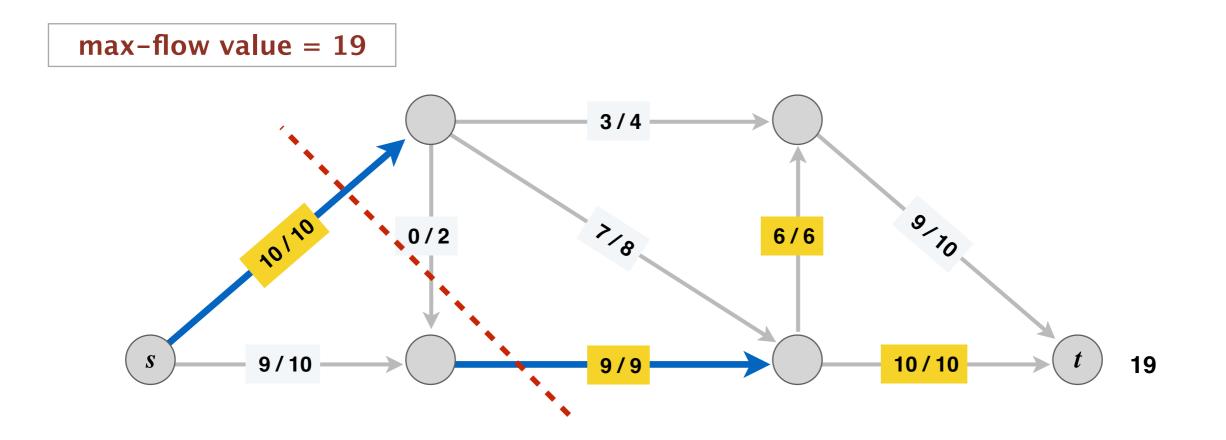
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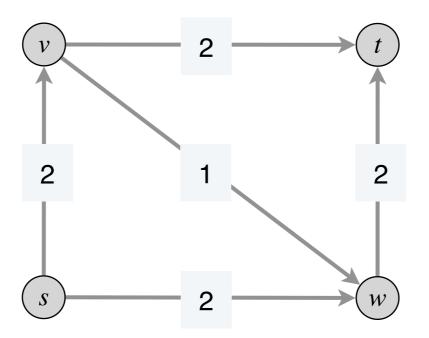
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Why Greedy Fails

Problem: greedy can never "undo" a bad flow decision

• Consider the following flow network



- Greedy could choose $s \rightarrow v \rightarrow w \rightarrow t$ as first *P*
- Takeaway: Need a mechanism to "undo" bad flow decisions

Ford-Fulkerson Algorithm

Ford Fulkerson: Idea

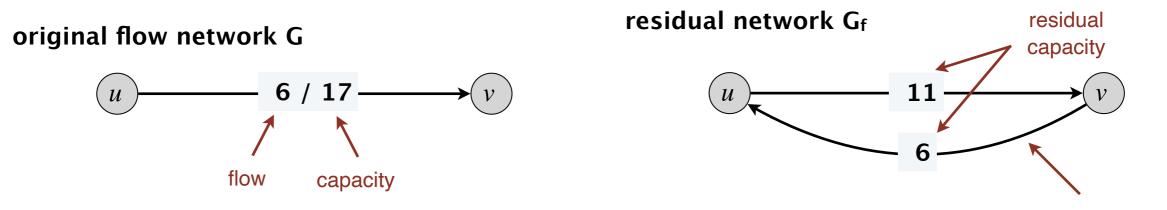
Goal: Want to make "forward progress" while letting ourselves undo previous decisions if they're getting in our way

- Idea: keep track of where we can push flow
 - Can push more flow along an edge with remaining capacity
 - Can also push flow "back" along an edge that already has flow down it (undo a previous flow push)
- Need a way to systematically track these decisions

Residual Graph

Given flow network G = (V, E, c) and a feasible flow f on G, the residual graph $G_f = (V, E_f, c_f)$ is defined as follows:

- Vertices in G_f same as G
- (Forward edge) For $e \in E$ with residual capacity c(e) f(e) > 0, create $e \in E_f$ with capacity c(e) f(e)
- (Backward edge) For $e \in E$ with f(e) > 0, create $e_{\text{reverse}} \in E_f$ with capacity f(e)



reverse edge

Flow Algorithm Idea

- Now we have a residual graph that lets us make forward progress or push back existing flow
- We will look for $s \thicksim t$ paths in G_f rather than G
- Once we have a path, we will "augment" flow along it similar to greedy
 - find bottleneck capacity edge on the path and push that much flow through it in G_f
- When we translate this back to G, this means:
 - We increment existing flow on a forward edge
 - Or we decrement flow on a backward edge

Augmenting Path & Flow

- An augmenting path P is a simple $s \sim t$ path in the residual graph G_f

Path that repeats no vertices

• The **bottleneck capacity** *b* of an augmenting path *P* is the minimum capacity of any edge in *P*.

	5	Some $s \sim t$ path P in G_f
	$\operatorname{AUGMENT}(f, P)$	
	$b \leftarrow$ bottleneck capacity of augmenting	path <i>P</i> .
	FOREACH edge $e \in P$:	
If/else update flow in G , not G_f	IF ($e \in E$, that is, e is forward edge)	
	Increase $f(e)$ in G by b	
	Else	
	Decrease $f(e)$ in G by b	
	Return f.	

Ford-Fulkerson Algorithm

- Start with f(e) = 0 for each edge $e \in E$
- Find a simple $s \sim t$ path P in the residual network G_f
- Augment flow along path ${\it P}$ by bottleneck capacity b
- Repeat until you get stuck

```
FORD-FULKERSON(G)

FOREACH edge e \in E: f(e) \leftarrow 0.

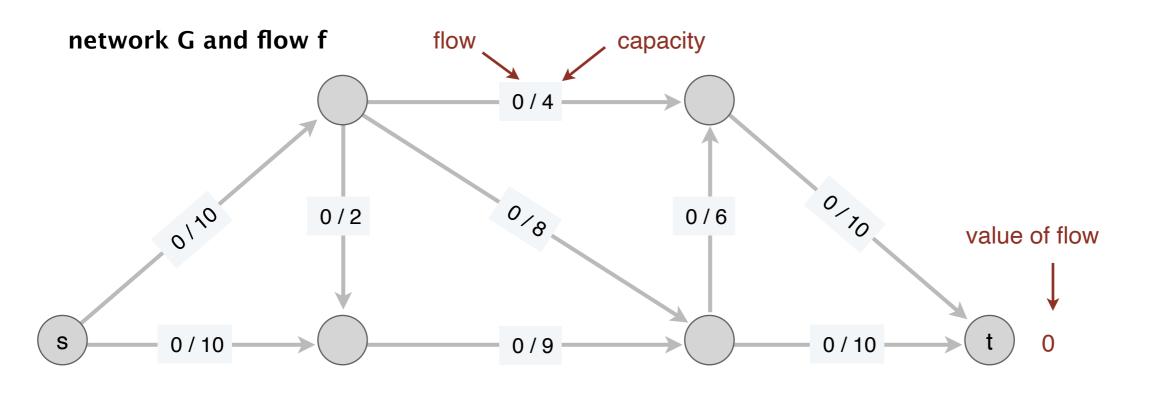
G_f \leftarrow residual network of G with respect to flow f.

WHILE (there exists an s¬t path P in G_f)

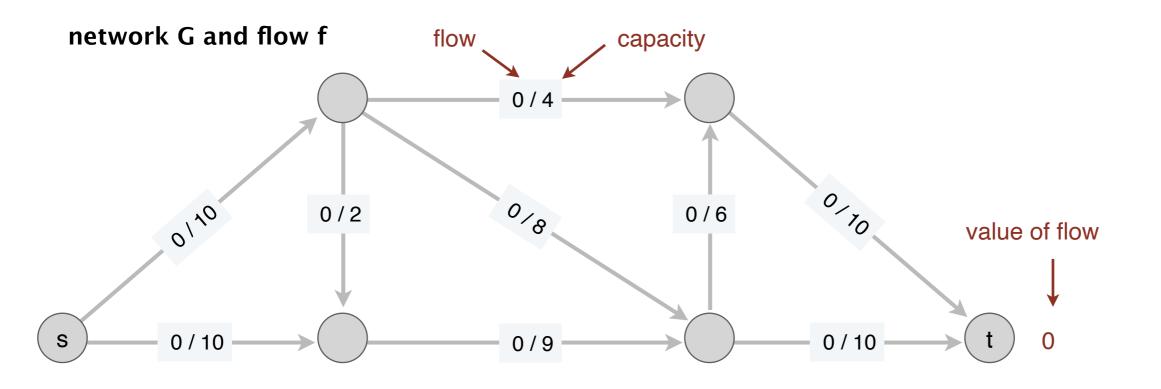
f \leftarrow AUGMENT(f, P).

Update G_f.

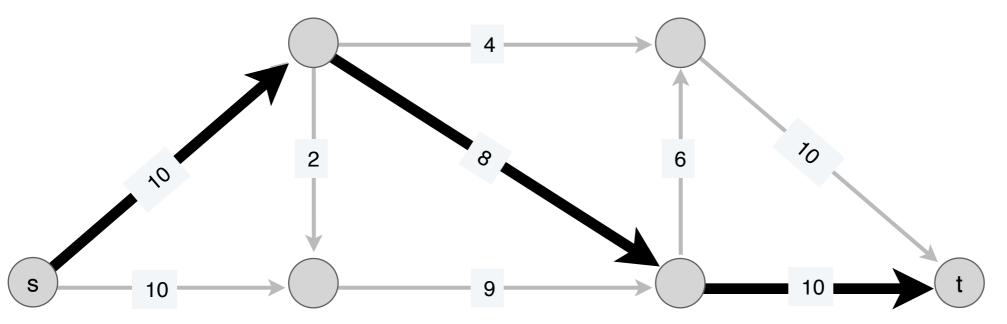
RETURN f.
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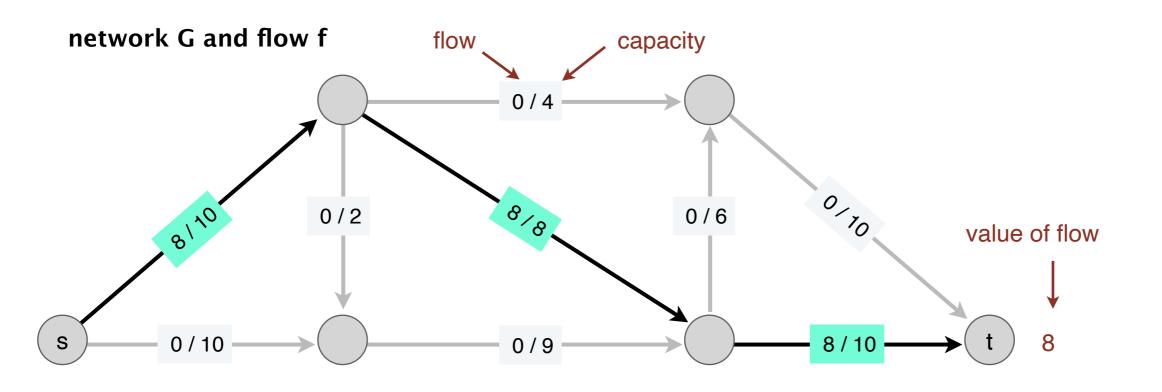


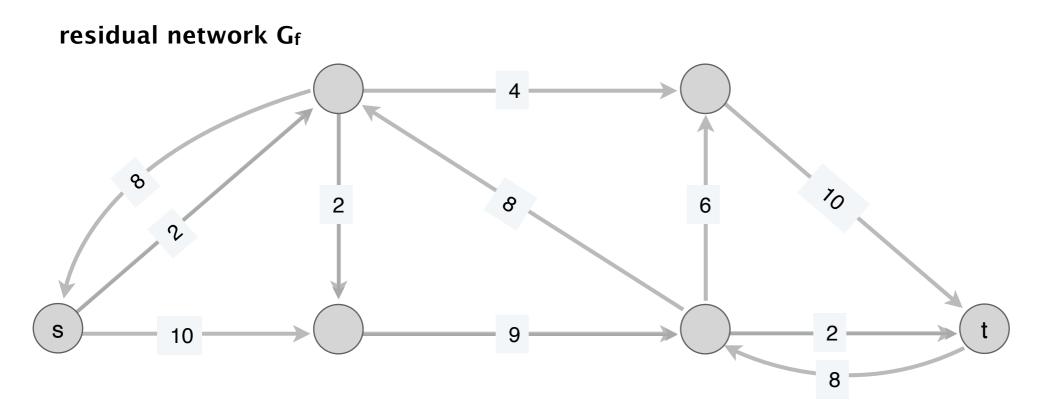
residual network G_f

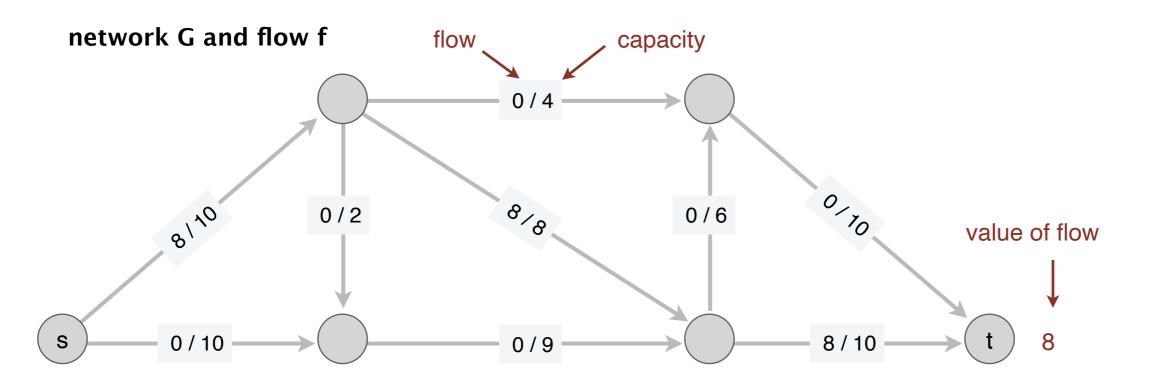


P in residual network G_f

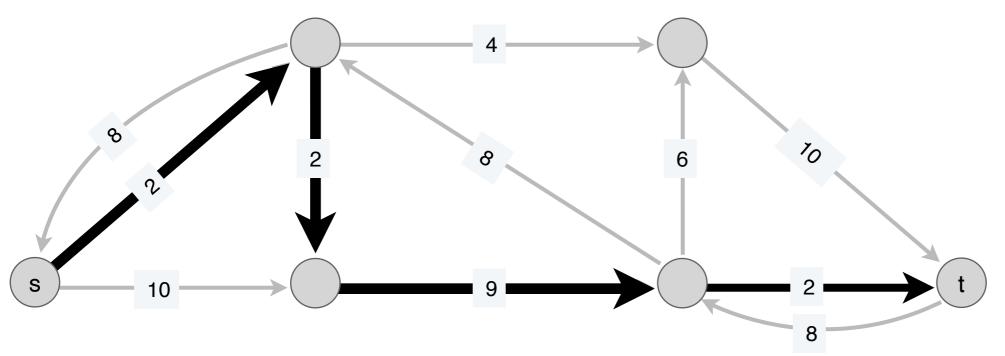


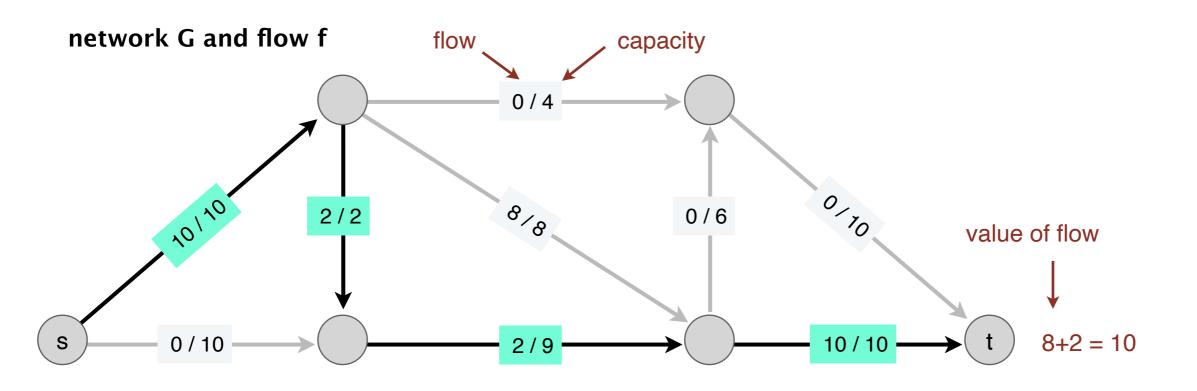




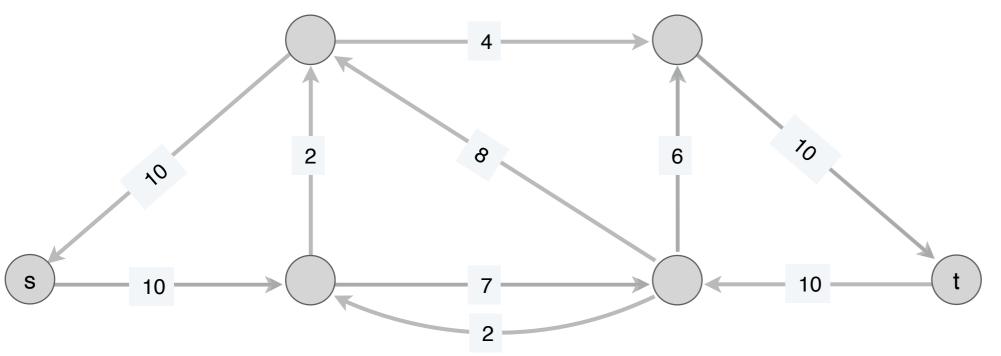


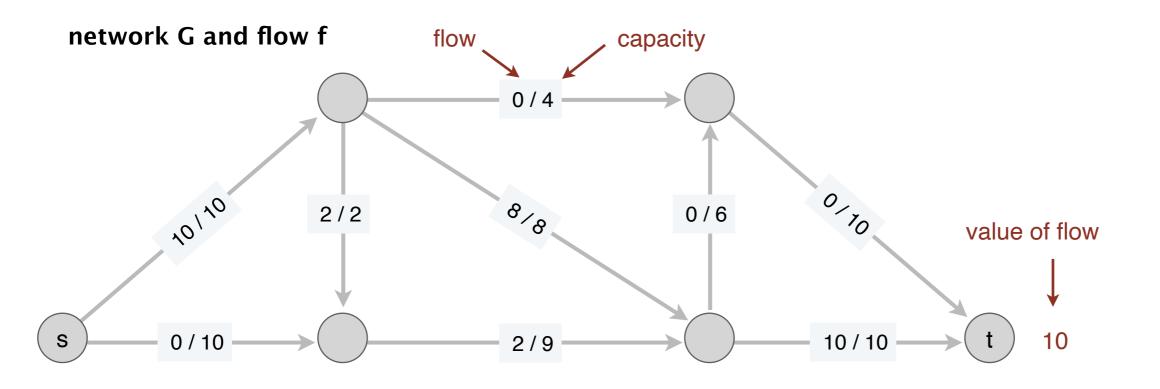
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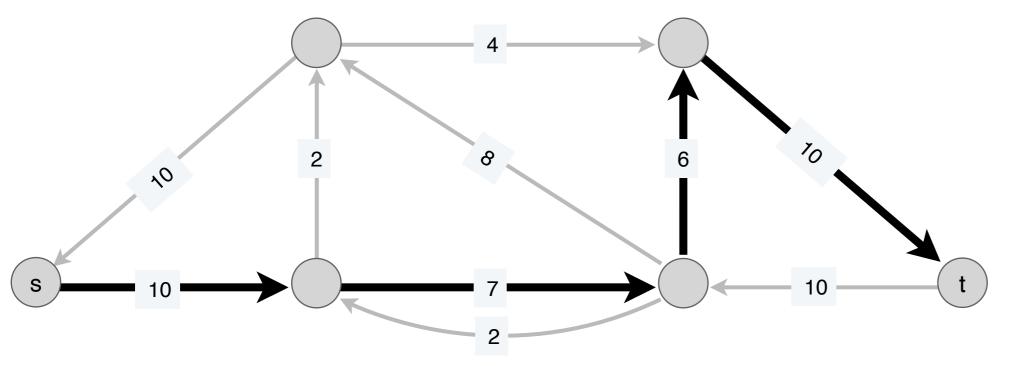


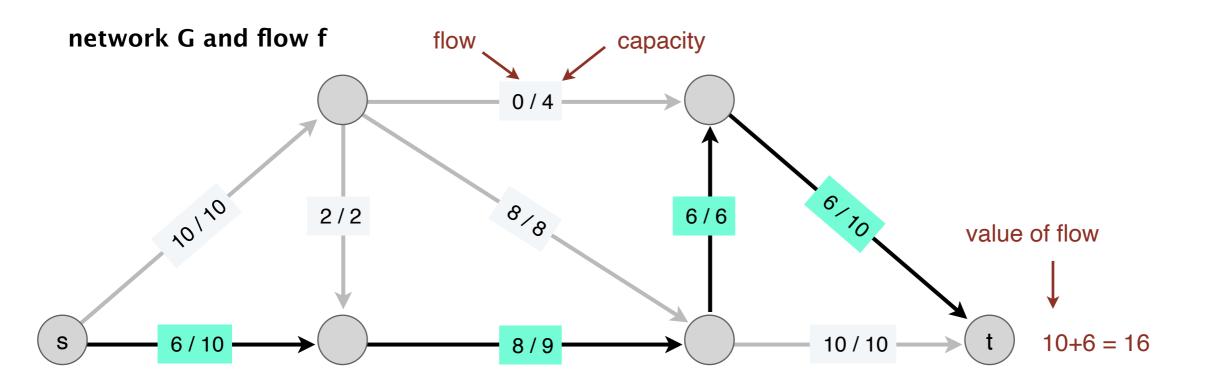
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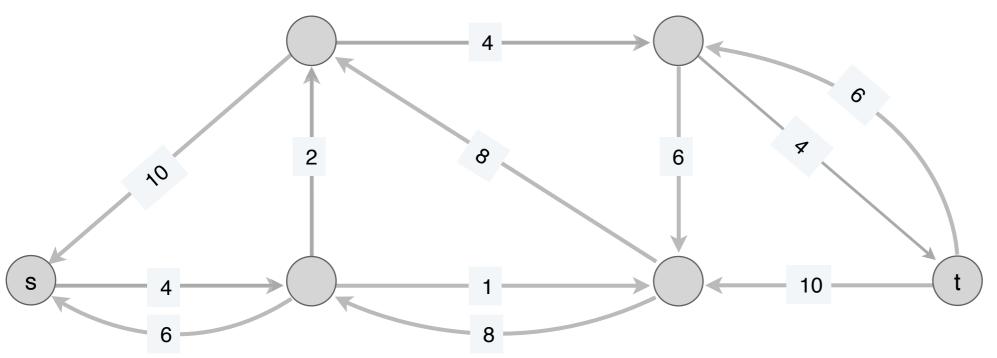


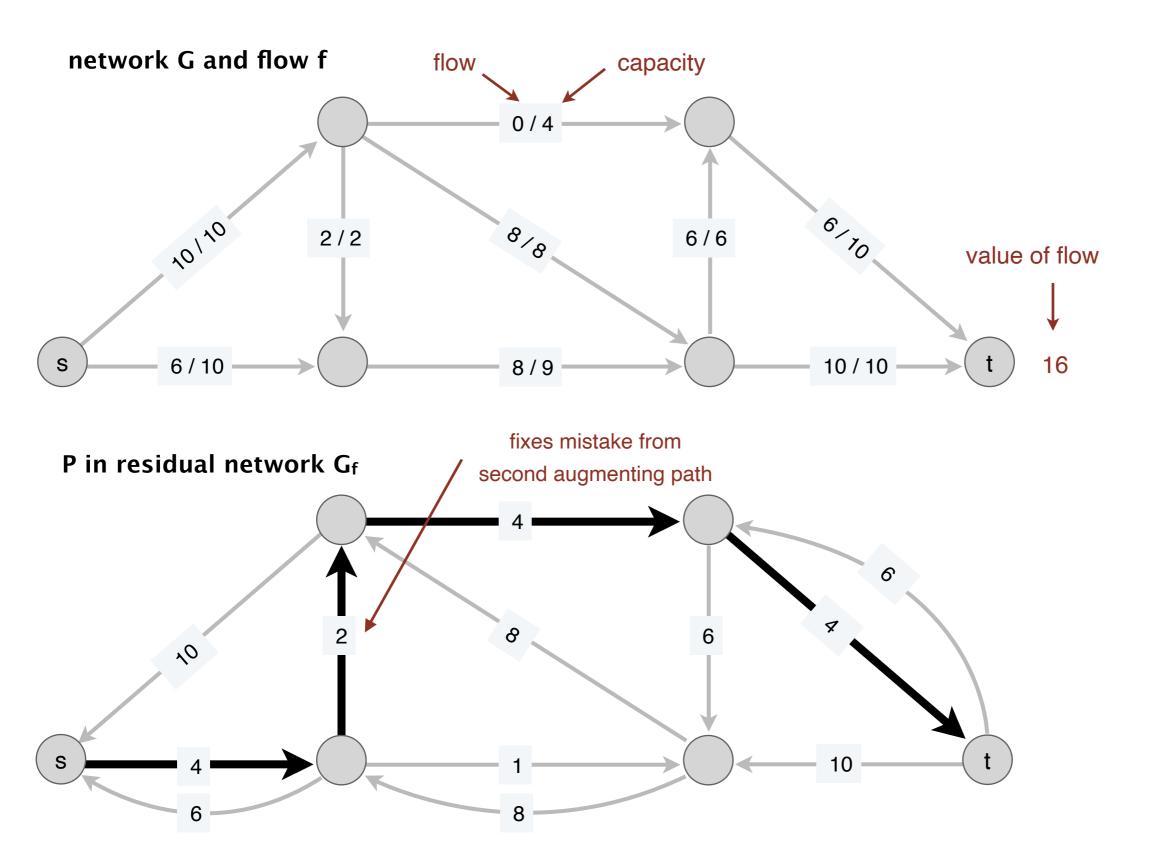
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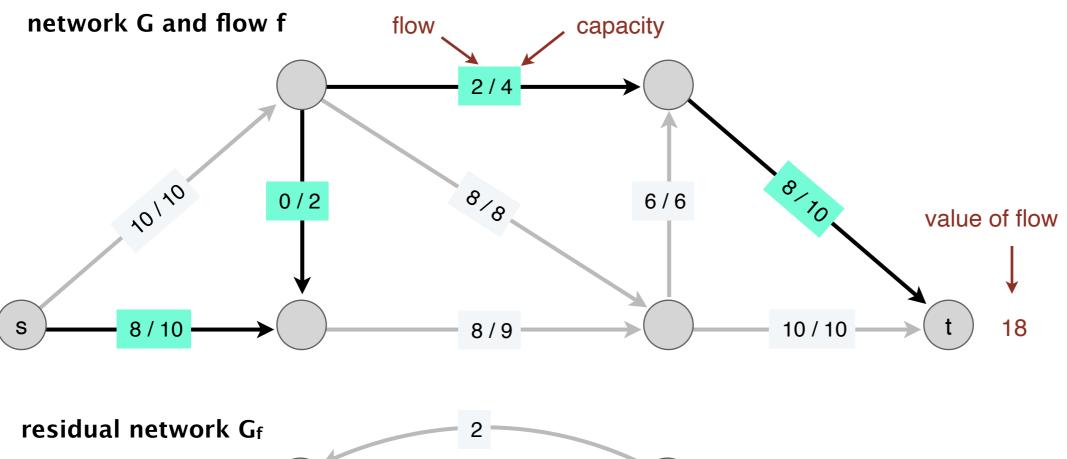


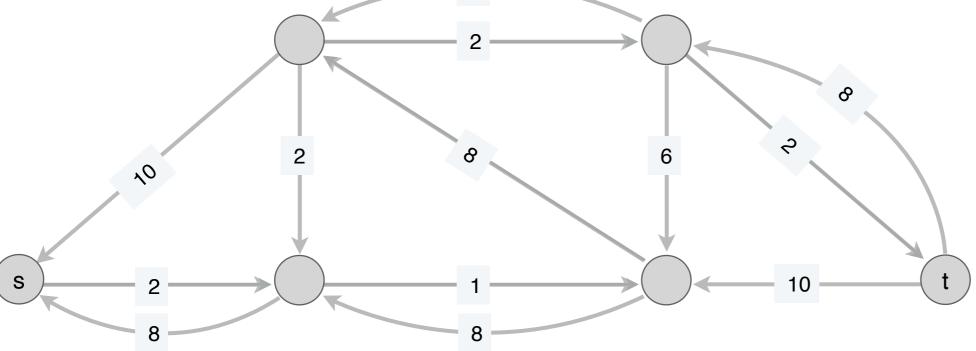


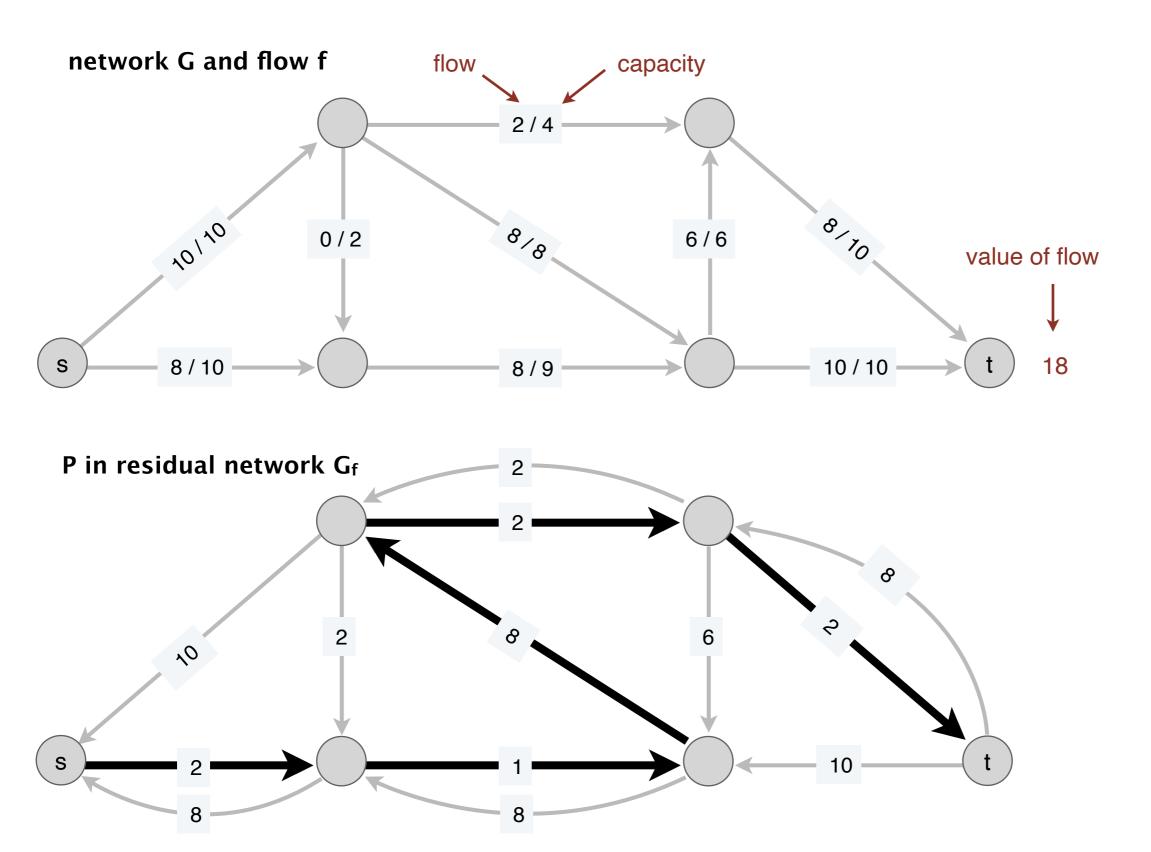
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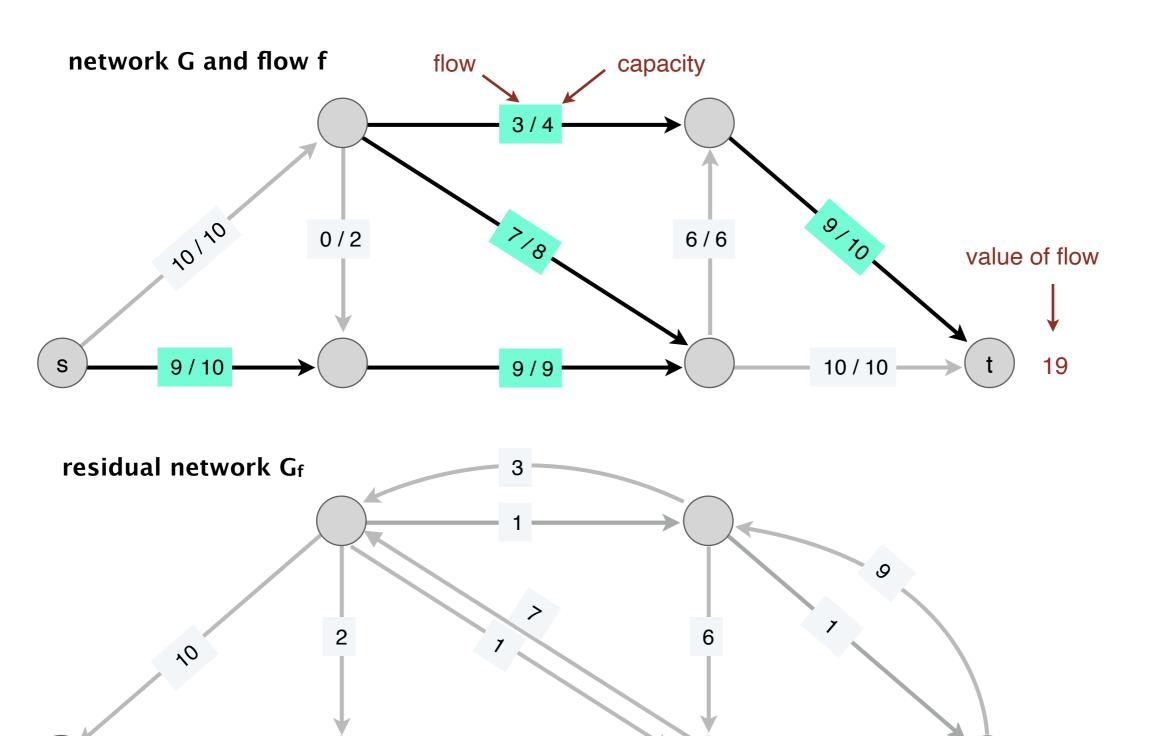




t

No s-t path left!

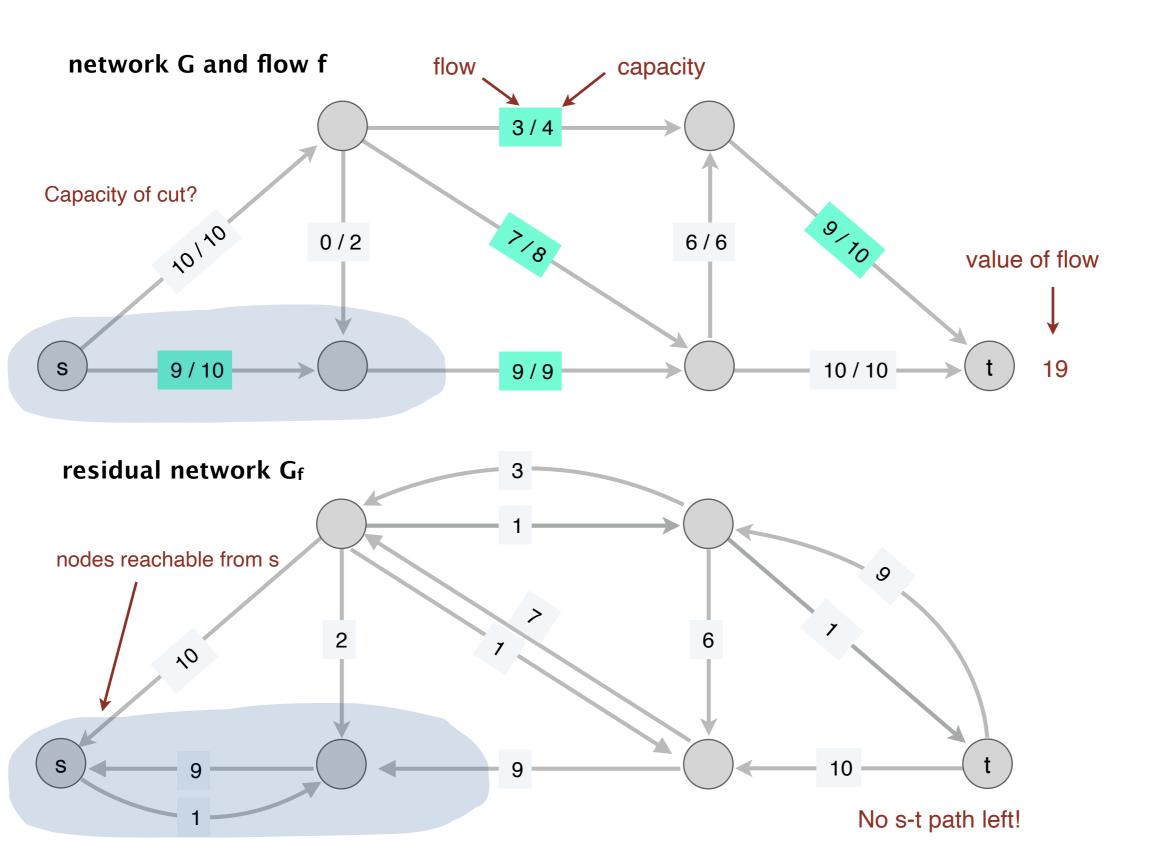
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Analysis: Ford-Fulkerson

Analysis Outline

- Feasibility and value of flow:
 - Show that each time we update the flow, we are routing a feasible *s*-*t* flow through the network
 - And that value of this flow increases each time by that amount
- Optimality:
 - Final value of flow is the maximum possible
- Running time:
 - How long does it take for the algorithm to terminate?
- Space:
 - How much total space are we using?

Feasibility of Flow

- Claim. Let f be a feasible flow in G and let P be an augmenting path in G_f with bottleneck capacity b. Let $f' \leftarrow \text{AUGMENT}(f, P)$, then f' is a feasible flow.
- **Proof**. Only need to verify constraints on the edges of P (since f' = f for other edges). Let $e = (u, v) \in P$
 - If *e* is a forward edge: f'(e) = f(e) + b

$$\leq f(e) + (c(e) - f(e)) = c(e)$$

• If *e* is a backward edge: f'(e) = f(e) - b

$$\geq f(e) - f(e) = 0$$

- Conservation constraint hold on any node in $u \in P$:
 - $f_{in}(u) = f_{out}(u)$, therefore $f'_{in}(u) = f'_{out}(u)$ for both cases

Value of Flow: Making Progress

• **Claim**. Let f be a feasible flow in G and let P be an augmenting path in G_f with bottleneck capacity b. Let

 $f' \leftarrow \text{AUGMENT}(f, P)$, then v(f') = v(f) + b.

- Proof.
 - First edge $e \in P$ must be out of s in G_f
 - (*P* is simple so never visits *s* again)
 - e must be a forward edge (P is a path from s to t)
 - Thus f(e) increases by b, increasing v(f) by $b \blacksquare$
- Note. Means the algorithm makes forward progress each time!

Acknowledgments

- Some of the material in these slides are taken from
 - Kleinberg Tardos Slides by Kevin Wayne (<u>https://www.cs.princeton.edu/~wayne/kleinberg-tardos/pdf/04GreedyAlgorithmsl.pdf</u>)
 - Jeff Erickson's Algorithms Book (<u>http://jeffe.cs.illinois.edu/</u> <u>teaching/algorithms/book/Algorithms-JeffE.pdf</u>)